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Bethesda, Md.

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HYDRODYNAMIC LOADING COEFFICIENTS FOR THE AGEN-1 MAIN STRUT-POD-FOIL SYSTEM AS DERIVED FROM THE 1975 FLAP INCIDENCE CONTROL EXPERIMENT,

> by David W. Coder Douglas E. Layne

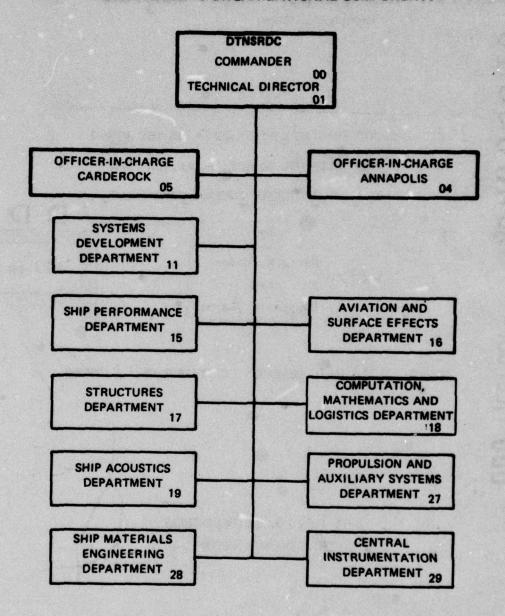
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SHIP PERFORMANCE DEPARTMENT DEPARTMENTAL REPORT



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20. ABSTRACT (Continue on reverse side if necessary and identify by block number)

As part of an investigation into minimizing control power requirements for hydrofoil craft, a technique has been developed for obtaining complete hydrodynamic lift and moment characteristics of a flapped hydrofoil from equilibrium data obtained in flap incidence control experiments with a freely pivoting foil. This method employs a simple mathematical model and various crossplots of the data to separate the effects of camber, foil incidence angle, and flap angle using a minimum amount of data. (cont'd

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Existing model data for the AGEH-1 main strut-pod-foil system under subcavitating conditions have been analyzed by this method, and effects of depth and velocity are described. Velocity effects were attributed to air and/or water flow out of the pod. Relatively high values of flap lift effectiveness (0.3 to 0.4) were obtained. Centers of pressure (lines of action) for lift due to camber, angle of attack, and flap angle are presented. Recommendations are given for improving the accuracy of the measurement and analysis techniques. . A. C today and D. C.

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b. Saib	Intercept of flap angle-foil angle curve (= (a) = 0)	Y or Y
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CHC	Camber moment coefficient	
CHOC	Foil-moment-curve slope (=3CH/3ec) avirages find	20
CH.	Flap-moment-curve slope (=3CH/36)	9
C,	Lift coefficient (= L/qS)	9
crc	Camber lift coefficient	
CLOC	Foil-lift-curve slope (=3C _L /3x)	
CLS	Flat-lift-curve slope (=2C _L /3e)	
C _M	Bias moment coefficient (=M/qSc)	
<u>c</u>	Mean geometric chord based on foil planform extended to centerline) pod
EH	Flap moment effectiveness (= C _{He} /C _{He})	
E _L	Flap lift effectiveness (= CLe/CLe)	
Н	Hydrodynamic moment	
h	Depth from free surface to foil	
L	Hydrodynamic lift	
M	Bias moment	
m	Slope of flap angle-foil angle curve (=)(/)(x)	
q	Dynamic pressure (= (1/2)eU ²)	
s	Planform area of foil extended to pod centerline	
U	Free stream velocity or carriage velocity	
W	Flap lift center of pressure location from the leading mean geometric chords	edge in

Foil pivot location from the leading edge in mean geometric X or x chords Planform lift center of pressure location from the leading Y or y edge in mean geometric chords Camber lift center of pressure location from the leading edge Z or z in mean geometric chords TERSTITIONS TORROW THIRE. Foil angle relative to pod agola ayaya teagba tiri Flap angle relative to foil l agole orrectances, a li Density of fluid 6 (Splint spaintfiles) slil

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As part of an investigation into minimizing control
power requirements for hydrofoil craft, a technique has
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simple mathematical model and various crossplots of the
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Existing model data for the AGEH-1 main strut-pod-foil system under subcavitating conditions have been analyzed by this method, and effects of depth and velocity are described. Velocity effects were attributed to air and/or water flow out of the pod. Relatively high values of flap lift effectiveness (0.3 to 0.4) were obtained. Centers of pressure (lines of action) for lift due to camber, angle of attack, and flap angle are presented. Recommendations are given for improving the accuracy of the measurement and analysis techniques.

ADMINISTRATIVE INFORMATION

The work presented here was sponsored by the Naval Sea Systems Command (NAVSEA SYSCOM) under Project S4606, Task 01703, and performed under the David W. Taylor Naval Ship Research and Development Center (DTNSRDC) Work Unit 1153-503.

INTRODUCTION

Of recent interest to the U.S. Navy have been methods of reducing the control power requirements for hydrofoil craft. In a theoretical study of four different hydrofoil configurations in a seaway, Remington

and Bender concluded that the configuration using a trailing edge flap for incidence control of a freely pivoting foil required the least amount of power. An existing model of the AGEH main strut-podfoil with a trailing edge flap on the foil has been modified for flap incidence control. The foil was made freely pivoting in pitch (incidence angle) about the existing transverse axis through the pod. The motion of the flap and foil angles were coupled together by a series of linkages to obtain a passive control system. An experiment performed at DTNSRDC using this modified model has been reported by Coder and Wisler. The purpose of that experiment, labeled here as the "1975 Flap Incidence Control Experiment," was to determine whether equilibrium flap-foil angle conditions ("stable flying situations") could be obtained. The velocities were low (7.31 to 12.86 m/s) so that the foil was fully wetted (no cavitation) for most of the conditions tested. Equilibrium conditions were obtained and are reported in Reference 2. While those data were being reduced, it was discerned that the moment at zero flap and foil angles and the variance of moment with flap angle alone could be obtained from the data using what will be called here the "indirect method." After those results were published, this "indirect method" was expanded to include consideration of the lift data (not published in Reference 2 but included here in Appendix A) to determine other hydrodynamic loading characteristics.

References are listed on page 79.

This model was previously used for work reported informally by A.C. Conolly in DTNSRDC Report SPD-332-H-02 in February 1973.

This "indirect method" is based on that two-dimensional representation of the foil developed in Coder, et al. 3 - the lift and moment were assumed to be the sum total of the parts due to foil camber, foil angle of attack, and tab/flap. Here the equations for lift and moment are written in coefficient form as given in Equations [1] and [2] of the ANALYSIS section. Using the straight-line fits to the flap angle-foil angle equilibrium data from Coder and Wisler, 2 and appropriate crossplots of those data and the lift data from Appendix A, the six coefficients on the right-hand side of Equations [1] and [2] are determined. Also, it will be seen that the lift and moment effectiveness and the lines of action of the various lift components may be determined from the resulting coefficients.

The objective of the present work is to determine with actual data whether this "indirect method" produces reasonable results. Since it is planned to conduct further flap incidence control experiments with an improved model and under cavitating conditions, this "indirect method" may prove to be a viable method to determine these lift and moment coefficients as a byproduct of studying the equilibrium conditions and the control system. Further, it may prove to be more advantageous from a testing point of view to determine the loading characteristics using this "indirect method" since much data is obtained rather quickly and efficiently.

The remainder of the report describes this "indirect method," presents and discusses the results for the data from the 1975 Flap Incidence Control Experiments, and makes recommendations as to the future employment of this method.

ANALYSIS

The lift and moment in coefficient form for a fully wetted flapped foil at small angles may be represented by

and we say the lost to the form of the form of the line and the line a

$$C_{L} = C_{Lo} + C_{LC} + C_{L\beta}$$

$$C_{H} = C_{Ho} + C_{HC} + C_{He}$$

where

C_L is lift coefficient (= lift/qS)

C_{Lot} is foil lift-curve slope (= 3C_L/3\alpha)

C_{LC} is camber lift coefficient (also includes thickness effects)

C_L is flap lift-curve slope (= 2C_L/26)

 C_{H} is moment coefficient (= moment/q $S\overline{c}$)

 $C_{H\alpha}$ is foil moment-curve slope (= $\partial C_{H}/\partial \alpha$)

C_{HC} is camber moment coefficient

C_H is flap moment-curve slope (= $\frac{\partial C_H}{\partial O}$)

is mean geometric chord based on foil planform extended to pod centerline

q is dynamic pressure (= $(1/2) e^{U^2}$)

s is planform area of foil extended to pod centerline

U is free stream velocity

3 is flap angle

e is density of fluid

The data reported by Coder and Wisler² pertain to a flapped, freely-pivoting foil and are presented in the form of foil angle versus flap angle to maintain hydrodynamic-external bias moment equilibrium, i.e.,

in the form

$$\beta = m \times + b$$
 [3]

where m is the slope $(=\frac{3}{3}/2\alpha)$

b is the intercept
$$(=(3)\alpha = 0)$$

From these data alone, C_{HC} and C_{HC} were calculated and are presented in that report. The present report also presents (in Appendix A) lift coefficient (C_L) versus foil angle (α) for that experiment. The slopes and intercepts of average straight-lines drawn through these data are presented in Table 1 together with pertinent data from Coder and Wisler. From all these data, the coefficients in Equations [1] and [2] and centers of pressure (lines of action) for the various lift components may be determined. A schematic showing the analysis technique is shown in Figure 1 and will now be described.

LIFT COEFFICIENTS

If Equation [3] is used with Equation [1]

$$C_{L} = C_{L\alpha} + C_{LC} + C_{L\beta} (m \times + b)$$

$$= (C_{L\alpha} + m C_{L\beta}) \times + (C_{LC} + bC_{L\beta})$$
[4]

Thus we have

$$(C_{L})_{\alpha} = 0 = C_{LC} + C_{L_{\alpha}} b$$

$$dC_{L}/d\alpha = C_{L\alpha} + C_{L_{\alpha}} m$$
[5]

In Figure 2, $(C_L)_{\bullet C} = 0$ from Table 1 is plotted versus b from Table 1 from which C_{LC} and C_{LC} were determined as the slope and intercept, respectively and listed in Table 2. In Figure 3, d_L/do_L from Table 1 is plotted versus m from Table 1. As seen in the figure, it is impossible to

TABLE 1 - FITTED DATA FROM 1975 FLAP INCIDENCE CONTROL EXP.

Velocity	h/z	M	CM	= 38/200	CONTROL OF THE PARTY OF THE PAR	COVERNMENT OF STREET	(CL) DEC
(m/s)		(N-M)		(Dog / Dog)	Special and Control Special Conference of the Control of the Contr	(1/Deg)	
7.31	0.578	0	0	0,681	-6.14	0.0467	0.0120
i i	1.156	0	0	0.665	-6.98	0.0527	-0.0050
	0,578	13.6	0.0160	0.594	-2,47	0.0503	0.0550
	1.156	13.6	0.0160	0.584	-3.70	0.0527	0.0450
	0.578	27.1	0.0319	0.699	0.76	0.0507	0.1050
	1.156	27.1	0.0319	0.647	-0.65	0.0547	0.0975
is Clabe.	0.578	40.7	0.0479	0,737	3.29	0.0513	0.1525
*	1,156	40.7	0.0479	0.707	1.56	0,0550	0.1400
9.00	0.578	0	0	0.757	-5.76	0.0497	0.0120
1	1.156	0	0	0.750	-7.16	0.0530	-0.0040
	0.578	13.6	0,0105	0.617	-4.09	0.0483	0.0320
	1.156	13.6	0.0105	0,611	-5,33	0.0517	0.0180
	0.578	27.1	0.0210	0.650	-2,78	0.0493	0.0530
	1.156	27.1	0.0210	0.611	-4.07	0.0523	0.0400
	0,578	40.7	0.0315	0,706	-0.81	0.0500	0.0860
*	1.156	40.7	0.0315	0.667	-2,20	0.0577	0.0710
10.55	0,578	0	0	0.907	-6.01	0.0493	0.0080
	1.156	0	0	0.904	-7,62	0.0527	-0.0080
	0,578	13.6	0.0077	0.641	-4.73	0.0477	0.0210
	1.156	13.6	0,0077	0.733	-6.33	0.0523	0.0060
	0.578	27.1	0.0153	0.661	-4.12	0.0570	0.0330
	1.156	27.1	0.0153	0.610	-5.88	00533	0,0170
	0.578	40.7	0.0230	0.667	-2.79	0.0493	0.0520
+	1.156	40.7	0.0230	0.654	-4.28	0.0547	0.0350
12.86	0.578	0	0	*	K	*	*
	1.156	0	0	*	*	*	*
	0.578	13.6	0.0052	*	*	*	+
	1.156	13.6	0.0052	*	*	.*	*
94 2.1 0	0.578	27.1	0.0103	0.736	-5.69	0.0497	0.0100
18 ST (28	1.156	27.1	0,0103	0.687	-6.90	0.0540	-0.0075
	0.578	40.7	0.0155	0.703	-4.88	0.0500	0.0200
+	1.156	40.7	0.0155	0.680	-6.07	0.0540	0.0080

* NO DATA OBTAINED

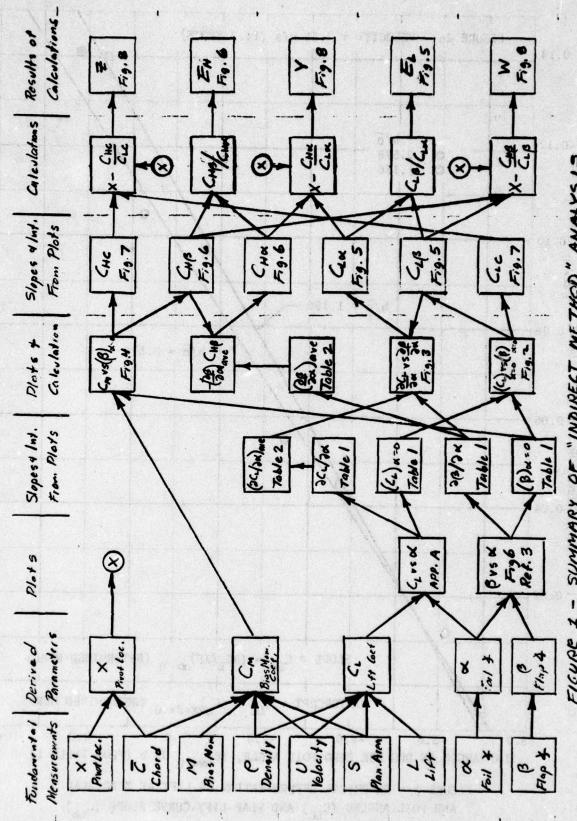


FIGURE 1 - SUMMARY OF "INDIRECT METHOD" ANALYS IS

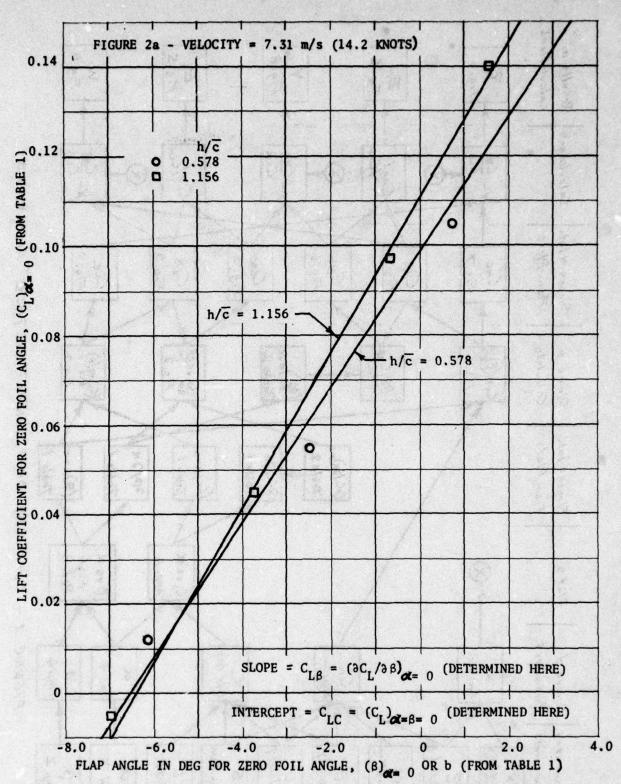
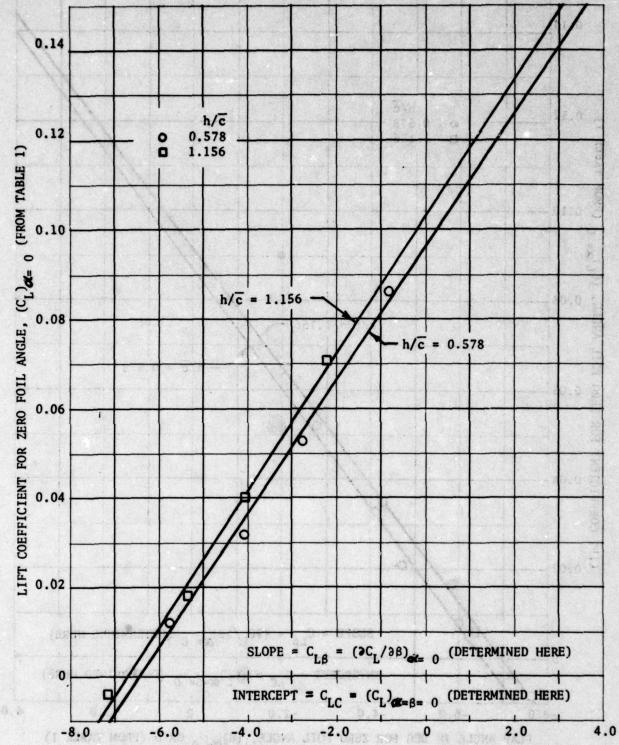
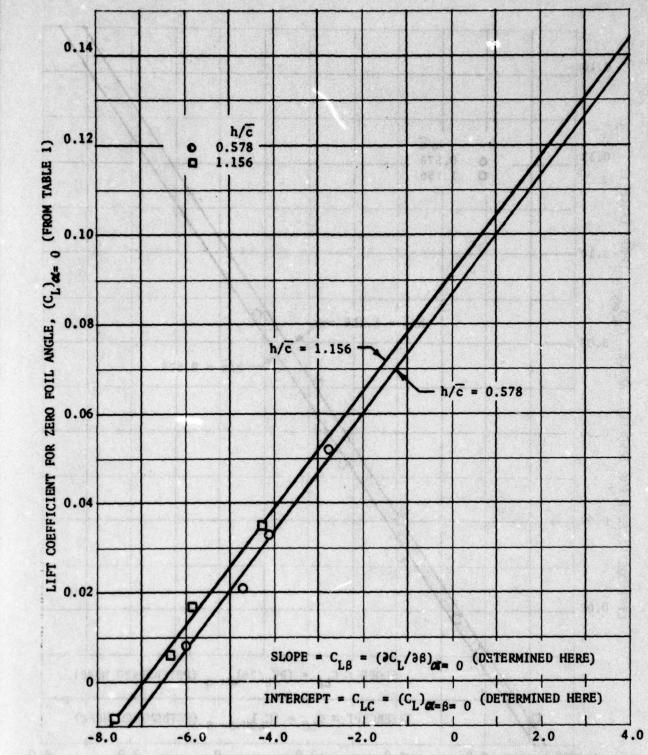


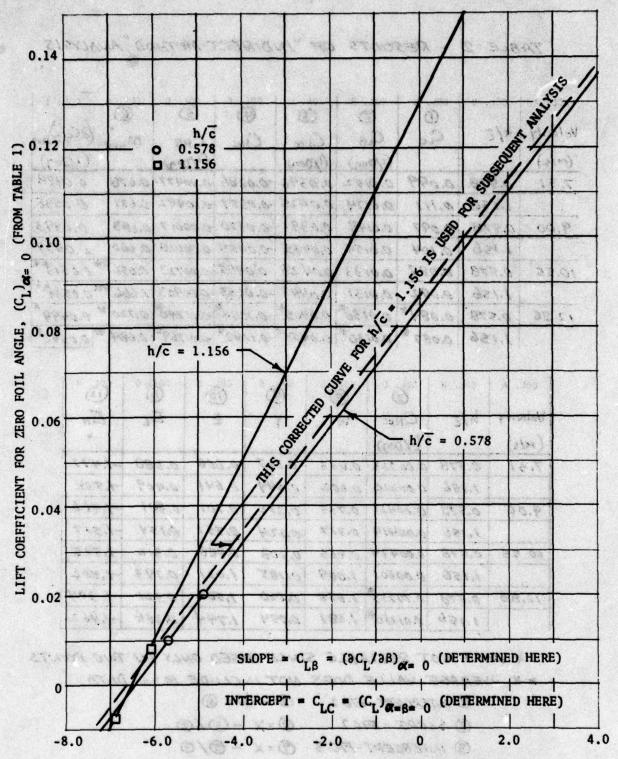
FIGURE 2 - GRAPHICAL DETERMINATION OF LIFT AT ZERO FLAP AND FOIL ANGLES (${
m C_{LC}}$) AND FLAP-LIFT-CURVE SLOPE (${
m C_{LS}}$)



FLAP ANGLE IN DEG FOR ZERO FOIL ANGLE, (β) OR b (FROM TABLE 1) FIGURE 2b - VELOCITY = 9.00 m/s (17.5 KNOTS)



FLAP ANGLE IN DEG FOR ZERO FOIL ANGLE, (β)_{α = 0} OR b (FROM TABLE 1) FIGURE 2c - VELOCITY = 10.55 m/s (20.5 KNOTS)



FLAP ANGLE IN DEG FOR ZERO FOIL ANGLE, (β) OR b. (FROM TABLE 1) FIGURE 2d - VELOCITY = 12.86 m/s (25.0 KNOTS)

TABLE 2 - RESULTS OF "INDIRECT METHOD" ANALYSIS

Velocity	4/Z	CLC	CLB	CLOC	Che	CHP (1/202)	Mave	COL. 1 (CL/Deg)
7.31	0.578	0.099	0.0152	0.0392	-0.0286	0.00477	0.678	0.0498
	1.156	0.111	0.0174	0.0425	-0.0357	0.00492	0.651	0.0538
9.00	0.578	0.097	0.0149	0.0391	-0.0370	0.00617	0.683	0.0493
	1.156	0.104	0.0154	0.0435	-0.0455	0.00618	0.660	0.0537
10.55	0.578	0.097	0.0133	0.04 26	-0.0495	0.00723	0.656	0.0513
	1.156	0.092	0.0131	0.0447	-0.0655	-0.00903	0.666	0.0534
12.86	0,578	0.084*	0.0130	0.0405	-0.1044	0.01740	0,720 K	0.0499
	A CONTRACTOR OF THE PERSONS ASSESSMENT	A STREET, SQUARE, SQUA	THE RESIDENCE OF THE PARTY OF T					0.0540

col. A Velocity (m/s)	k/z	CHAL (Voes)	© W	COLOE Y	@ 2	EL.	E _H
7.31	0.578	0,00323	0.633	0.237	0.608	0.388	-1.477
	1.156	0.00320	0.602	0.244	0.641	0.409	7.538
9.00	0.518	0.00421	0.733	0,212	0.701	0.381	1,466
	1.156	0.00414	0.727	0.224	0.757	0.354	1.517
10.55	0.578	0.00474	0.863	0,208	0.888	0.312	1.525
	1.156	0.00601	1,009	0.195	1.031	0.293	1,502
12.86	0.578	0.01253	1.658	0.010	1,562	0.321	1.387
	1.156	0.01210	1.681	0.054	1.794	0.286	-1.462

* DATA NOT RELIABLE SINCE BASED ONLY ON TWO POINTS * A AVERAGE VALUE DOES NOT INCLUDE M = 0 DATA

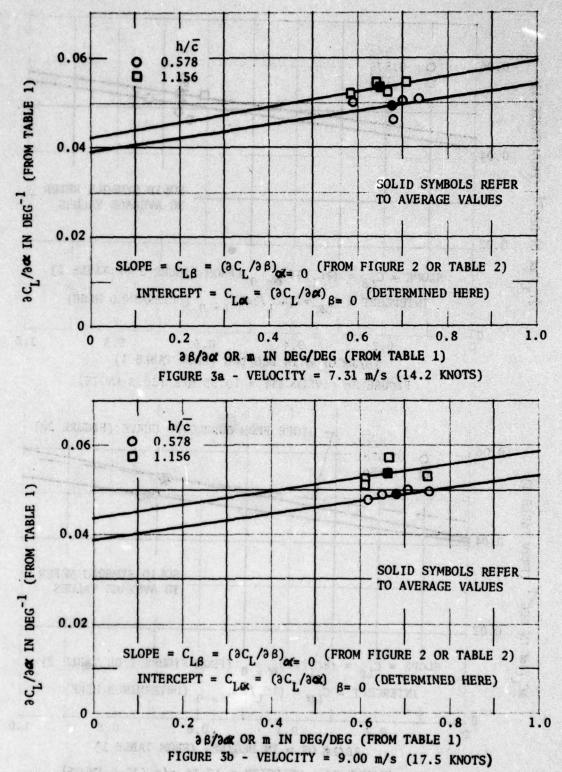
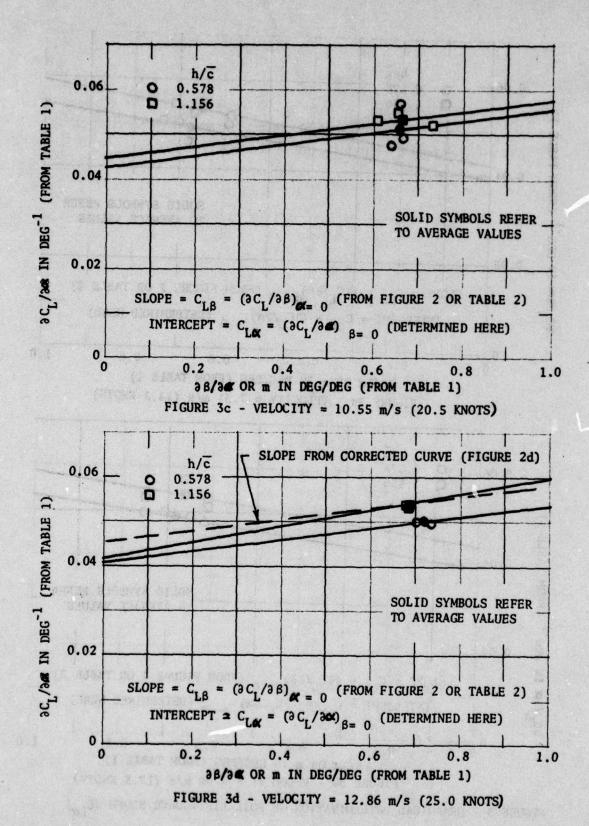


FIGURE 3 - GRAPHICAL DETERMINATION OF FOIL-LIFT-CURVE SLOPE (C. ...)



draw a straight line through the data so that an accurate value for $C_{L^{\alpha}}$ and $C_{L^{\alpha}}$ could be obtained from the slope and intercept, respectively. However, since the appropriate slope for the straight line, $C_{L^{\alpha}}$, has already been determined from Figure 2, it was used to draw the straight line in Figure 3 so that the intercept, $C_{L^{\alpha}}$, could be obtained. $C_{L^{\alpha}}$ determined this way is also listed in Table 2.

MOMENT COEFFICIENTS

Since the hydrodynamic moment (C_H) and the bias moment (C_M) together are zero for a free foil,

From Equation [2],

or

$$\beta = -[(C_{M} + C_{HC})/C_{Hp}] - [C_{Hac}/C_{Hp}] \propto$$

From Equation [3] we have

so,

$$m = -(C_{HK}/C_{HK})$$

$$b = -(C_{M} + C_{HC})/C_{HK}$$
or,

$$C_{M} = (-C_{HC}) + (-C_{HK}) b$$

By plotting C_M from Table 1 versus b from Table 1 in Figure 4, $-C_{H}$ and $-C_{HC}$ were determined as the slope and intercept, respectively. Then using m averaged over the bias moments from Table 1 and C_{H} as determined

CHOC = -m CHO

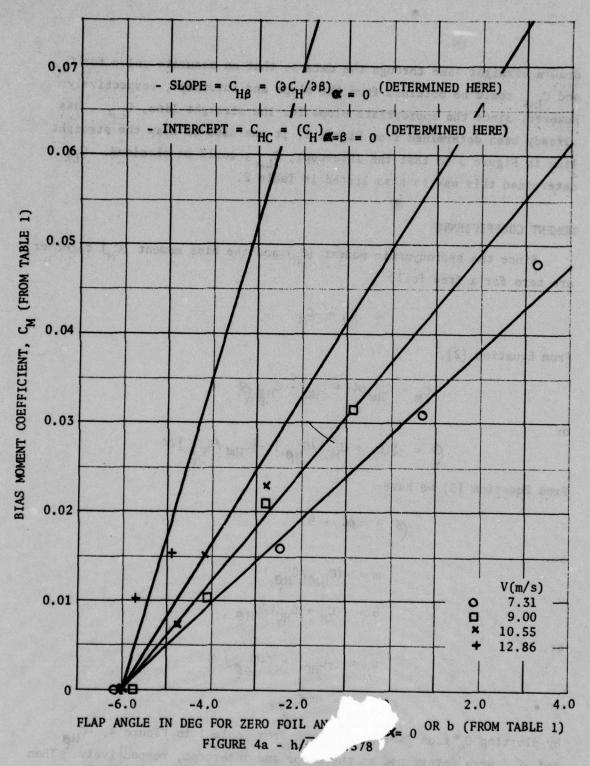
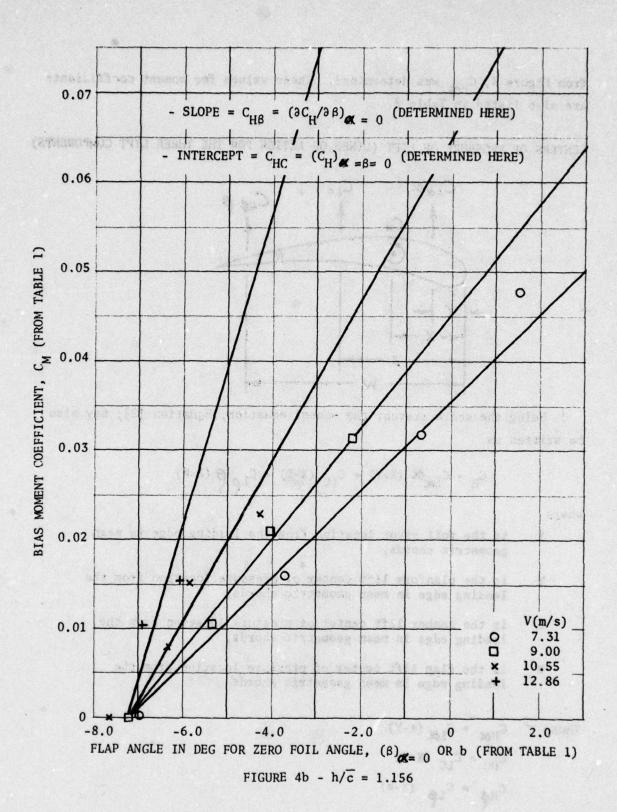
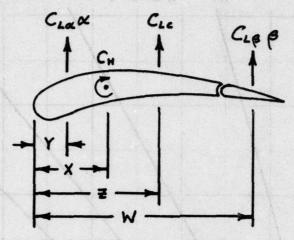


FIGURE 4 - GRAPHICAL DETERMINATION OF MOMENT AT ZERO FLAP AND FOIL ANGLES ($^{\rm C}_{\rm HC}$) AND FLAP-MOMENT-CURVE SLOPE ($^{\rm C}_{\rm H\beta}$)



from Figure 4, C_{Hoc} was determined. These values for moment coefficients are also listed in Table 2.

CENTERS OF PRESSURE OF LIFT (LINES OF ACTION FOR THE THREE LIFT COMPONENTS)



Using the above sketch, the moment equation, Equation [2], may also be written as

$$C_{H} = C_{L\alpha} \times (X-Y) + C_{LC} (X-Z) + C_{L\alpha} \times (X-W)$$

where

- X is the foil pivot location from the leading edge in mean geometric chords,
- Y is the planform lift center of pressure location from the leading edge in mean geometric chords,
- Z is the camber lift center of pressure location from the leading edge in mean geometric chords,
 - W is the flap lift center of pressure location from the leading edge in mean geometric chords

Thus,
$$C_{HX} = C_{LX}(X-Y)$$

$$C_{HC} = C_{LC}(X-Z)$$

$$C_{HX} = C_{LX}(X-W)$$

or,

$$Y = X - C_{H\alpha} / C_{L\alpha}$$

$$Z = X - C_{HC} / C_{LC}$$

$$W = X - C_{H\alpha} / C_{L\alpha}$$

Thus, the location of these centers of pressure of lift (or lines of action for the three lift components) were calculated from the hydrodynamic coefficients and are listed in Table 2.

FLAP EFFECTIVENESS

The flap lift and moment effectiveness, respectively are defined as

$$E_{L} = C_{L_{\phi}} / C_{L_{\alpha}}$$

$$E_{H} = C_{H_{\phi}} / C_{H_{\alpha}}$$

These were also calculated from the coefficients and are listed in Table 2.

RESULTS

When viewing the results of the analysis presented in Figures 5 through 8, it should be noted that the analyzed results for 12.86 m/s are not reliable since data for only two bias moments (instead of four) were obtained and analyzed. For this reason, the hand-faired curves through the analyzed results in the figures are dashed when extending the results from 10.55 m/s to 12.86 m/s. For most cases, these results for 12.86 m/s, do however, follow the general trends established from the lower velocities.

As shown in Figure 5, over the range of model depths and velocities, the flap lift-curve slope ($^{\rm C}_{\rm L}$) increases slightly with increasing depth and decreases slightly with increasing velocity. The foil lift-curve slope ($^{\rm C}_{\rm Loc}$) increases with increasing depth and increasing velocity.

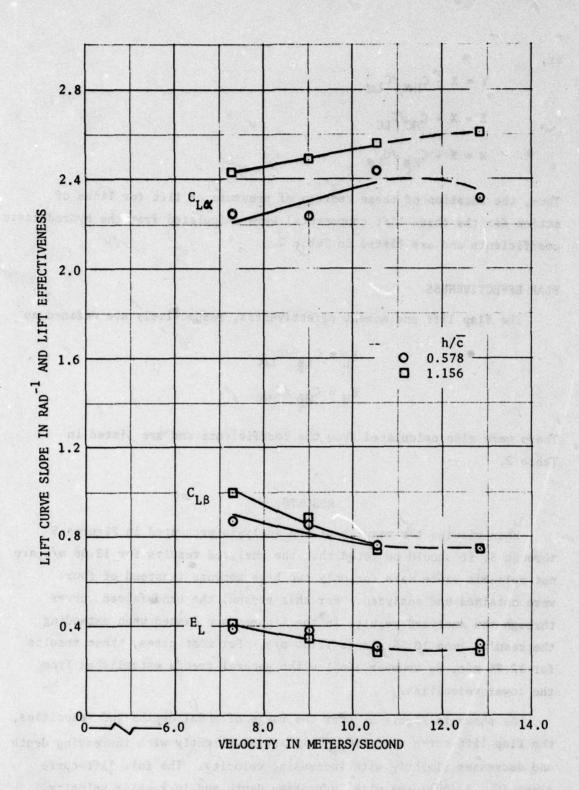


FIGURE 5 - LIFT CURVE SLOPES AND FLAP LIFT EFFECTIVENESS VERSUS VELOCITY

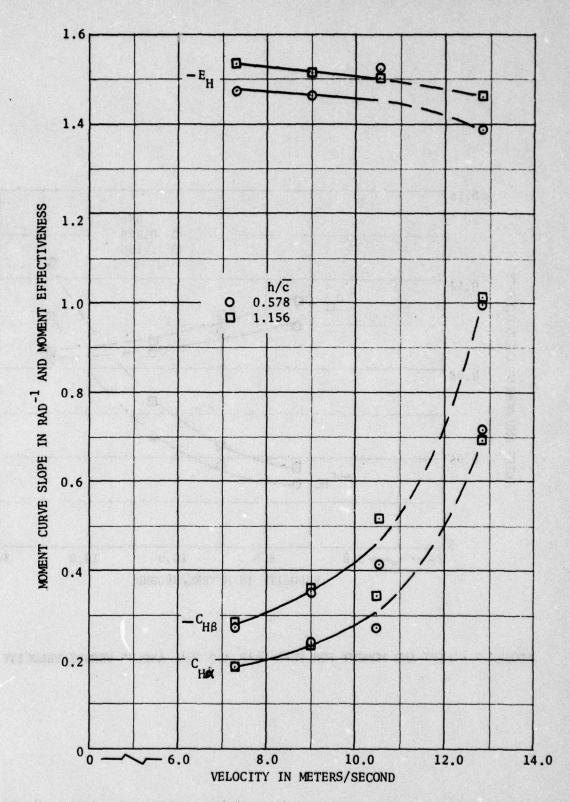


FIGURE 6 - MOMENT CURVE SLOPES AND FLAP MOMENT EFFECTIVENESS VERSUS VELOCITY

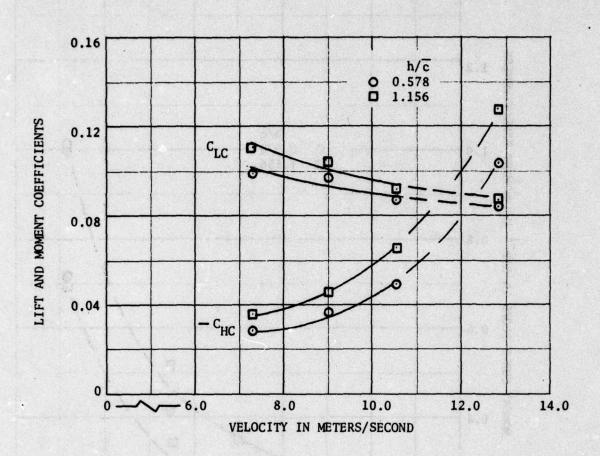


FIGURE 7 - LIFT AND MOMENT FOR ZERO FLAP AND FOIL ANGLES VERSUS VELOCITY

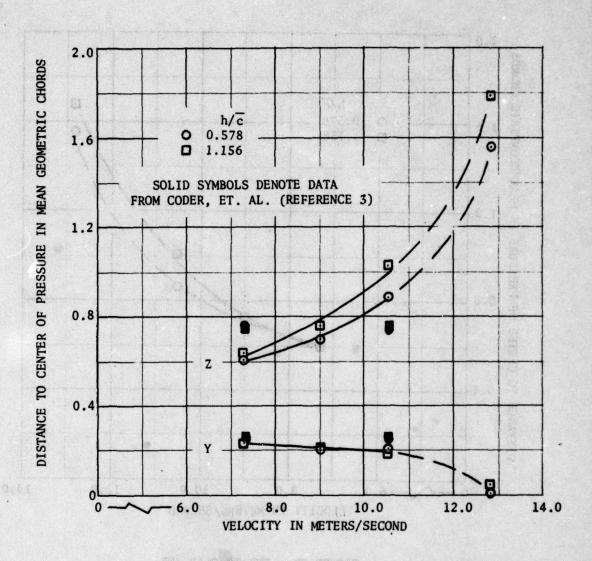


FIGURE 8a - DUE TO PLANFORM (Y) AND CAMBER (Z)

FIGURE 8 - CENTER OF PRESSURE OF LIFT DUE TO PLANFORM (Y), CAMBER (Z), AND FLAP (W)

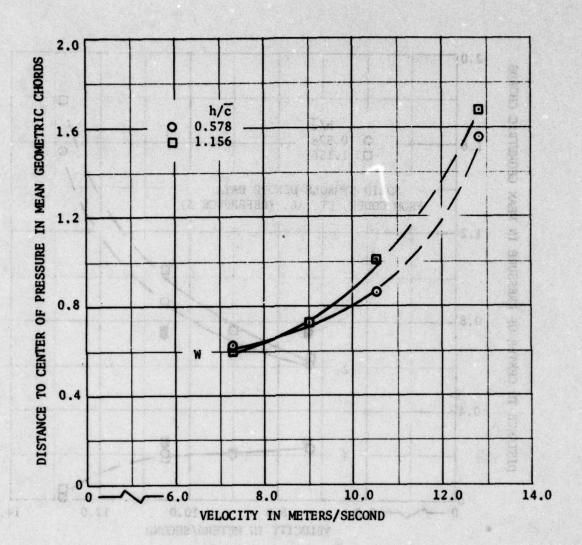


FIGURE 8b - DUE TO FLAP (W)

The resulting flap lift effectiveness $(E_L = C_{L_0} / C_{L_0})$ shows no depth dependence but a slight decrease with increasing velocity.

In Figure 6, depth has a very small effect on the flap moment-curve slope (C_{H}) and the foil moment-curve slope (C_{H}) . Both $-C_{H}$ and C_{H} increase significantly with increasing velocity. When the flap moment effectiveness $(E_{H} = C_{H})$ is calculated, the effect of depth is more easily discernible -- its magnitude is larger for larger depths. The magnitude of E_{H} decreases slightly with increasing velocity.

The lift and moment coefficients for zero flap and foil angles are shown in Figure 7. The magnitudes of the coefficients are larger for the larger depth. The lift coefficient for zero flap and foil angles (C_{LC}) decreases somewhat and the negative of the moment coefficient for zero flap and foil angle ($-C_{HC}$) increases significantly with increasing velocity. This large increase in the magnitude of this moment coefficient is due to the aft movement of the center of pressure of lift due to camber ($Z = X - C_{HC}/C_{LC}$) as shown in Figure 8. This center of pressure is slightly more aft for the larger depth.

The center of pressure of lift due to planform (Y = X - C_{Hoc}/C_{Loc}) moves slightly forward with velocity up to 10.55 m/s and approaches the leading edge (near zero) for 12.86 m/s. The center of pressure of lift due to flap (W = X - C_{Hoc}/C_{Loc}) is slightly more aft at the larger depth and moves aft with increasing velocity. Thus, it is seen that the two centers of pressure Z and W shift with velocity such as to cause a larger negative moment (pitching leading edge downward) with increasing velocity and Y shifts slightly more forward to cause a larger positive moment.

DISCUSSION

The foregoing analysis and results show that it is possible to obtain the six hydrodynamic lift and moment coefficients from a foil that is freely pivoting, has a controllable flap with suitable feedback control system, and has provision for externally applied bias moments.

The coefficients such obtained are not as accurate as those that might be obtained by direct measurement. For example, the flap lift curve slope could be obtained more accurately by fixing the foil at a set angle (say zero) and measuring the lift while varying the flap angle. The present method does, however, provide a simple determination of the coefficients from a relatively small body of data. When using this method, it would be best to ensure that for every condition (velocity and depth) data were obtained for at least three bias moments and preferably four.

The most significant result of the analyzed results is the drastic shift in centers of pressure due to velocity (shown in Figure 8). For a similar foil (but without a flap) at the lower velocities (7.31 and 10.55 m/s), it was determined by Coder, et al that Y (Planform Center) was near the quarter chord and Z (Camber Center) was at about the threequarter chord with no apparent effect of velocity. These results are shown on Figure 8a for a comparison with the present data. The present data shows a greater dependence on velocity. It is thought that the effect of velocity on the centers of pressure of the data analyzed here might well be due to small amounts of water and/or air leaking out of the pod into the flow. The experiment described in Reference 4 had one pushrod passing vertically through the strut which was a possible path for atmospheric air leakage to the pod and foil. An attempt was made to seal the strut to prevent this source of leakage. Whenever this was done, it was found that the resulting hydrodynamic coefficients became constant for the two velocities. In the present experiment, discussed in Reference 2, it was more difficult to seal the strut because two linkages passed vertically through the strut and it was imperative that the sealing technique not increase friction in the linkages. Little, if any, air was observed during testing. However, it is apparent now that there might have been enough leakage to influence the results.

The large shifts in centers of pressure at the higher velocities (10.55 and 12.86 m/s) may be partly due to the license used in drawing the straight line fits through the data during the analysis procedure. For example, the straight lines drawn on Figure 4 were drawn through the

average of $(\bullet)_{\bullet C_{=}}$ for C_{M} = 0 of the three lower velocities. It is seen that the resulting lines drawn for the larger velocities of 10.55 and 12.86 m/s are steeper and have larger intercepts than those that might be drawn through the actual data points for the particular velocity alone. This would result in a larger $-C_{HC}$, $-C_{HC}$ and C_{HC} (since this is determined as -m C_{Hp}) than what ordinarily might be determined. Thus, Y, Z, W, and E_{H} are affected by this interpretation -- Y might be too small, and Z, W, and $-E_{H}$ too large. This would tend to make the results show a weaker dependence on velocity.

A detailed error analysis is performed in Appendix B. Estimated maximum errors in the fundamental experimental measurements were determined and followed through the analysis step by step. Error bands for the hydrodynamic coefficients, centers of pressure, and effectiveness were thus obtained. This error analysis shows that there could be considerable errors apparently resulting mainly from the inaccuracy of the flap angle measurement. Improvement in this measurement and perhaps foil angle and bias moment could improve the results considerably.

CONCLUSIONS

- 1. The technique developed in this report permits determination of the hydrodynamic loading coefficients characteristics on a freely pivoting foil with controllable flap, a suitable control system, and external applied bias moments. Measurement of lift, foil angle, and flap angle must be made and the bias moment known.
- 2. To use this technique effectively, data for several values of bias moment are required. At least three values, and preferably four, for each velocity and depth should be used.
- A critical step in the analysis is drawing the straight line fits.
 Varying the approach can alter the results.
- 4. Error bands for the hydrodynamic coefficient, centers of pressure, and effectivenesses could be considerably improved by an improvement in the flap angle measurement. Lesser amounts of improvement could be obtained by improving the foil angle and bias moment measurements.

5. The data of Reference 2 is not a good representation of the full-scale AGEH system. The present analysis suggests that there was air/water leaking down the strut and out of the pod into the flow.

RECOMMENDATIONS

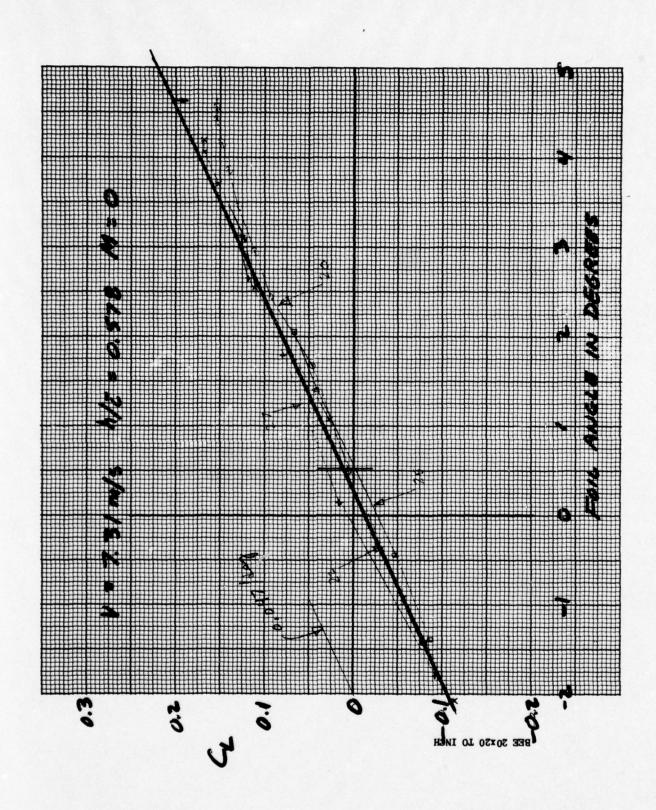
- 1. In future experiments employing the present technique, data for four values of bias moment should be obtained for each velocity and depth.
- 2. In future experiments to determine hydrodynamic coefficients, etc., by the "indirect method", the flap angle measurement should definitely be improved. Also further improvement of the results could be obtained by improving the foil angle and bias moment measurements.
- 3. The experiment should be extended into the region of cavitating condition to see what effect cavitation has on the hydrodynamic characteristics and the "indirect method" analysis technique.

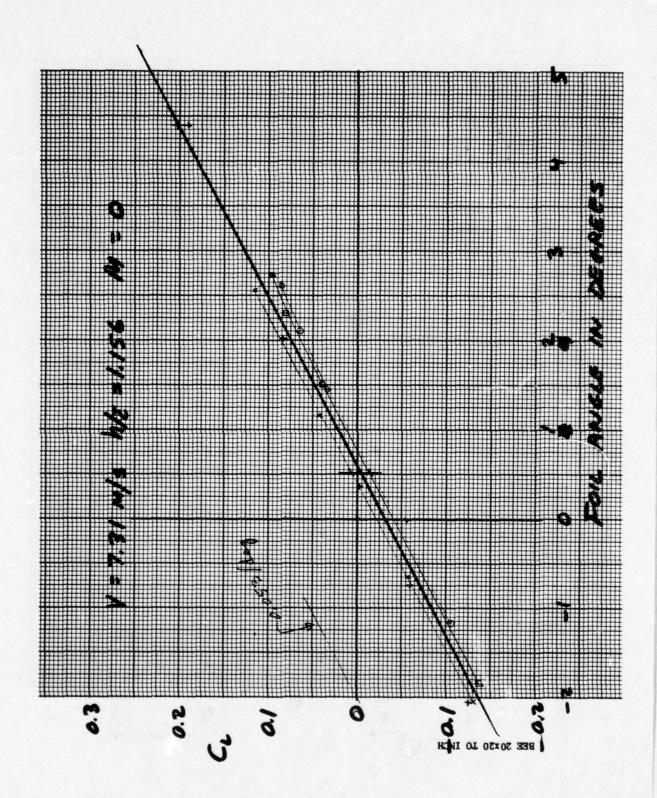
ACKNOWLEDGEMENTS

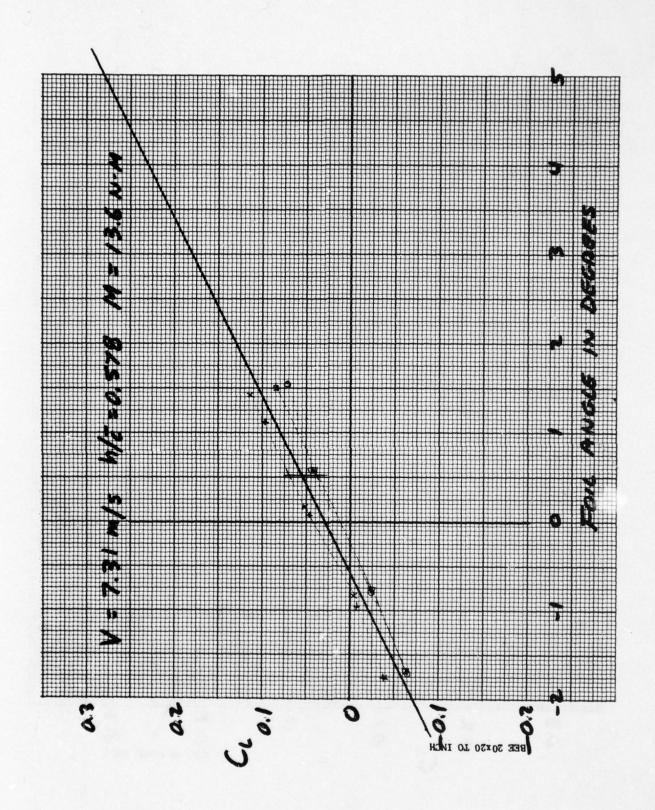
The authors of this report wish to acknowledge that the data they analyzed here came from experimental work in which Mr. Lester B. Moore, Mr. Michael F. Jeffers, and Mr. Bejamin B. Wisler were instrumental.

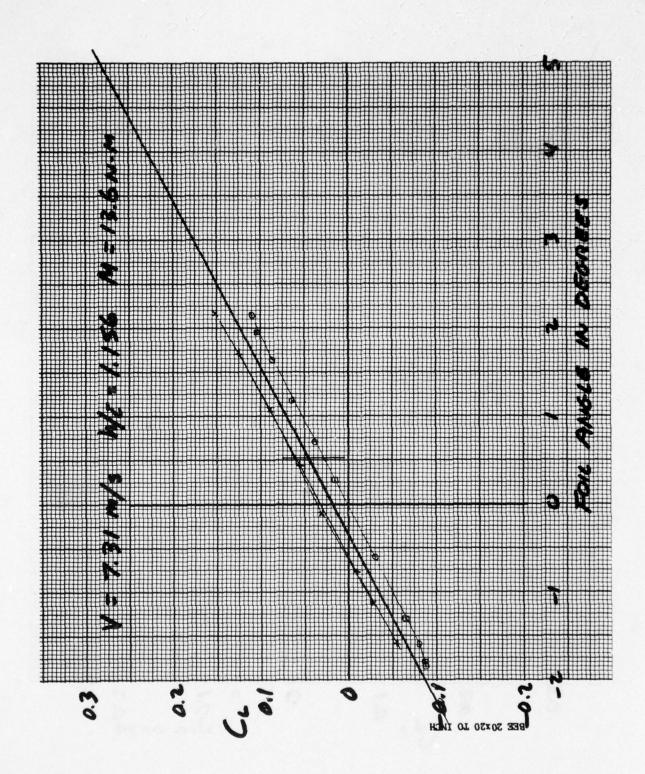
APPENDIX A

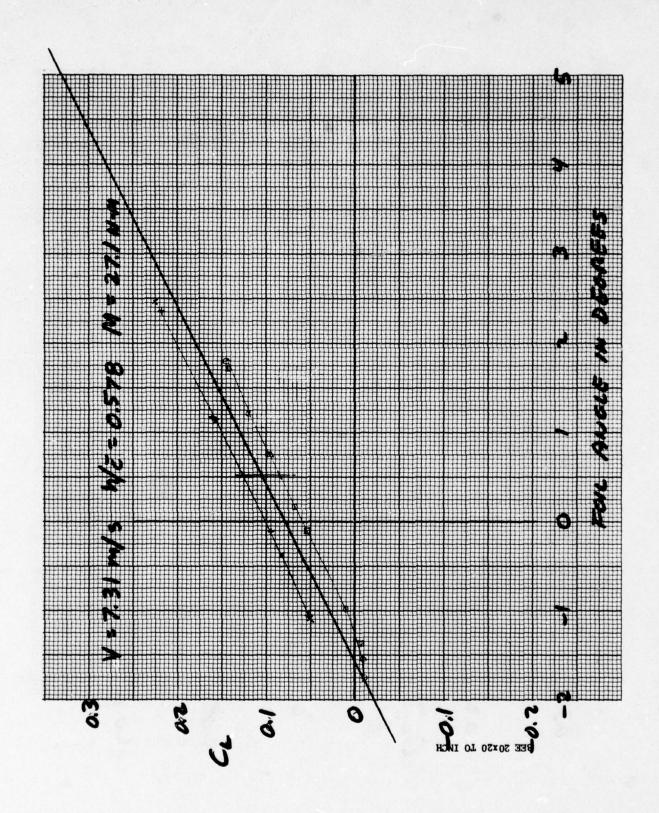
LIFT COEFFICIENT VERSUS FOIL ANGLE FROM THE 1975 FLAP INCIDENCE CONTROL EXPERIMENT

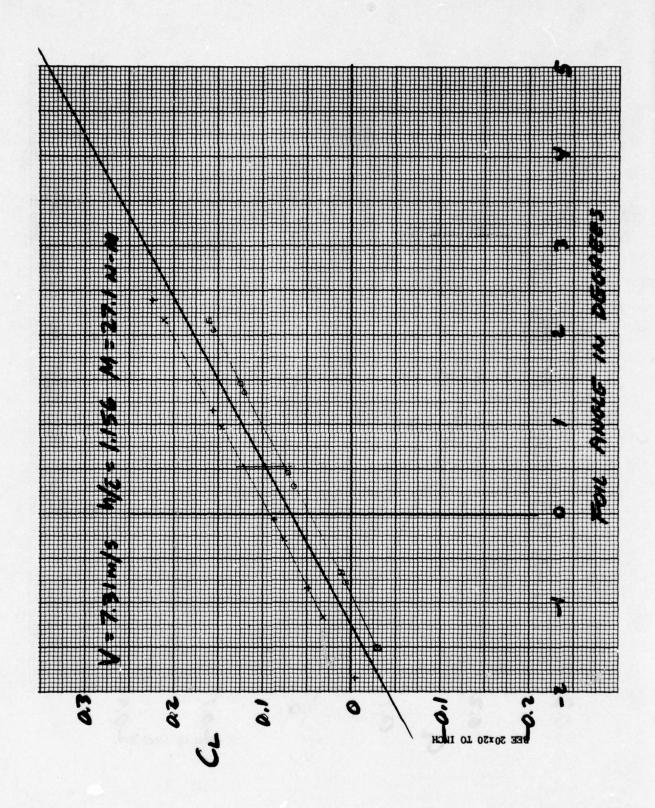


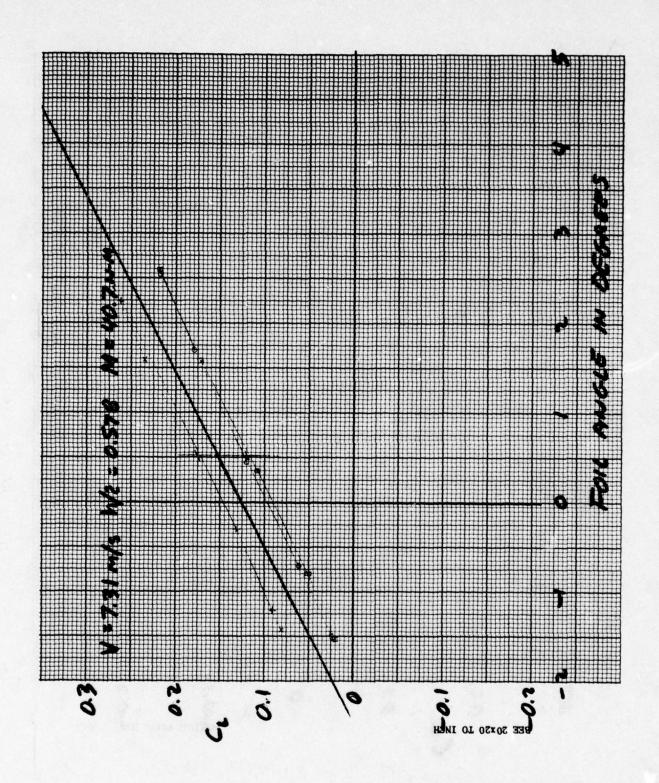


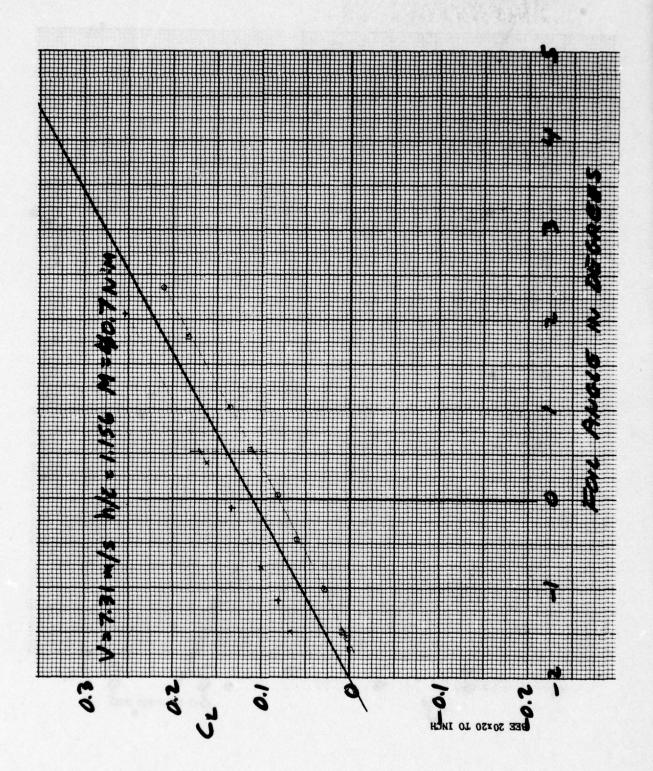


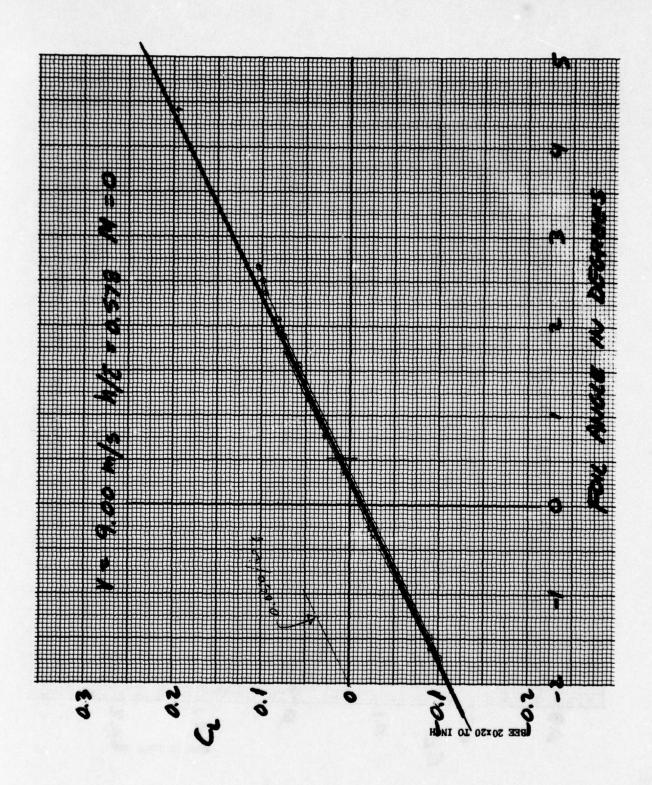


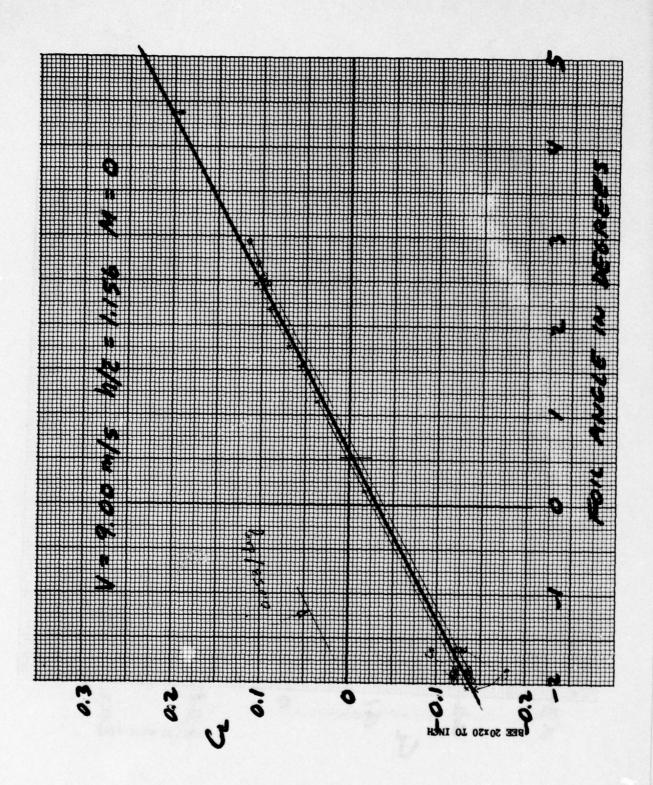


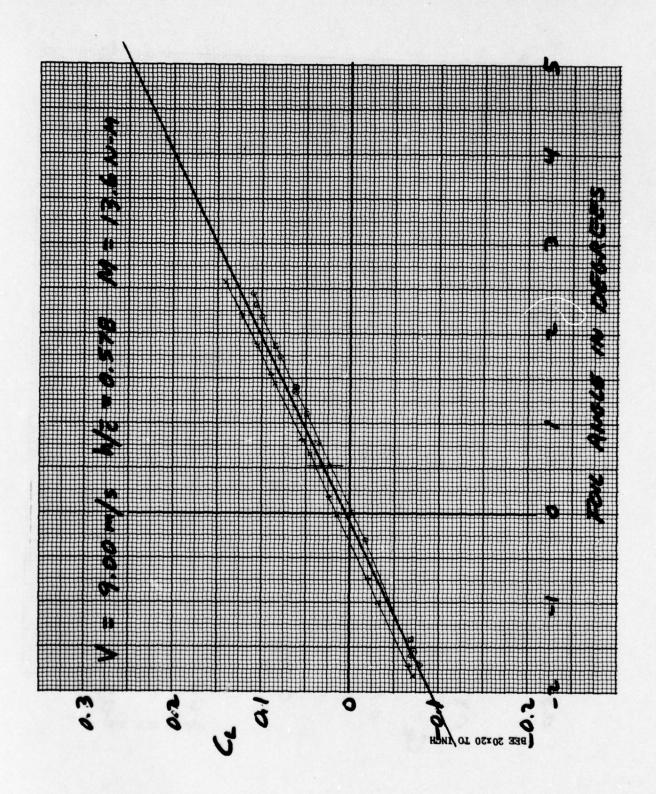


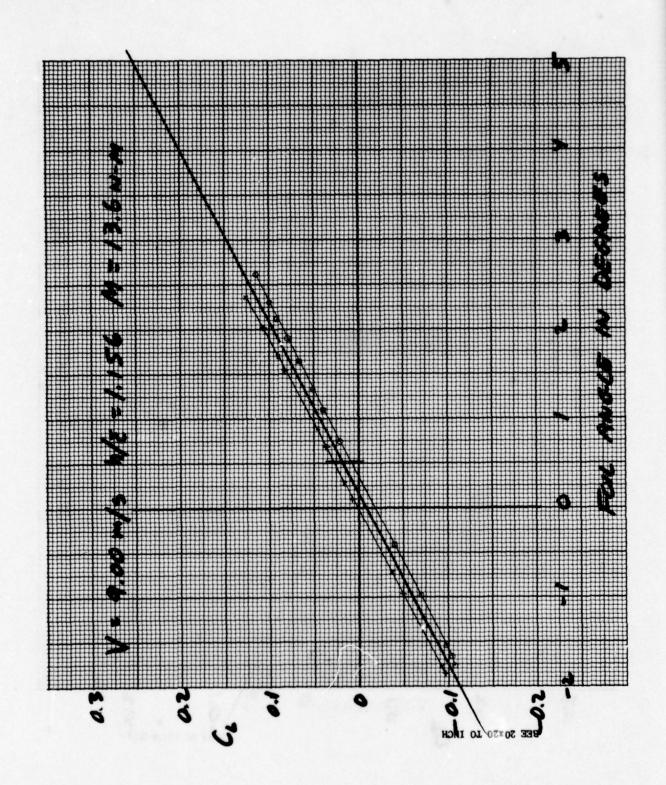


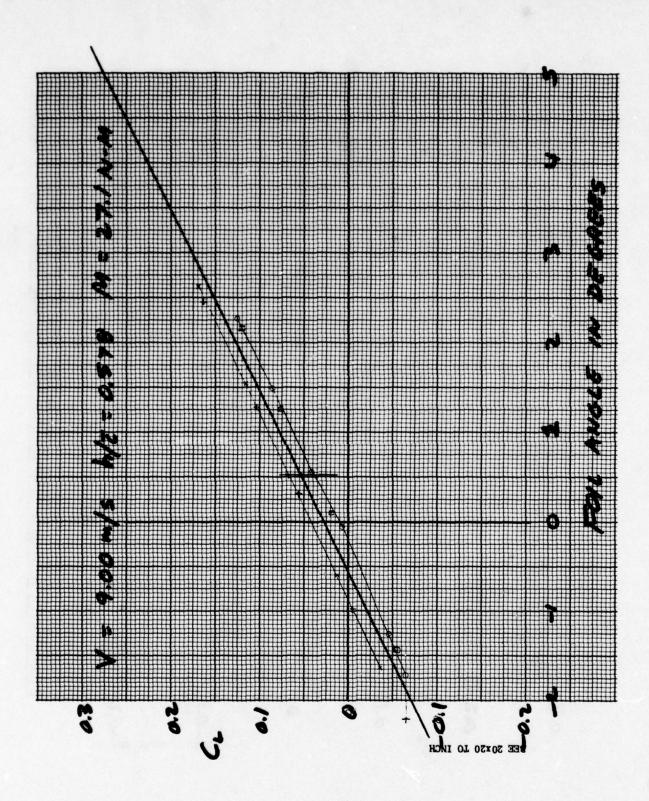


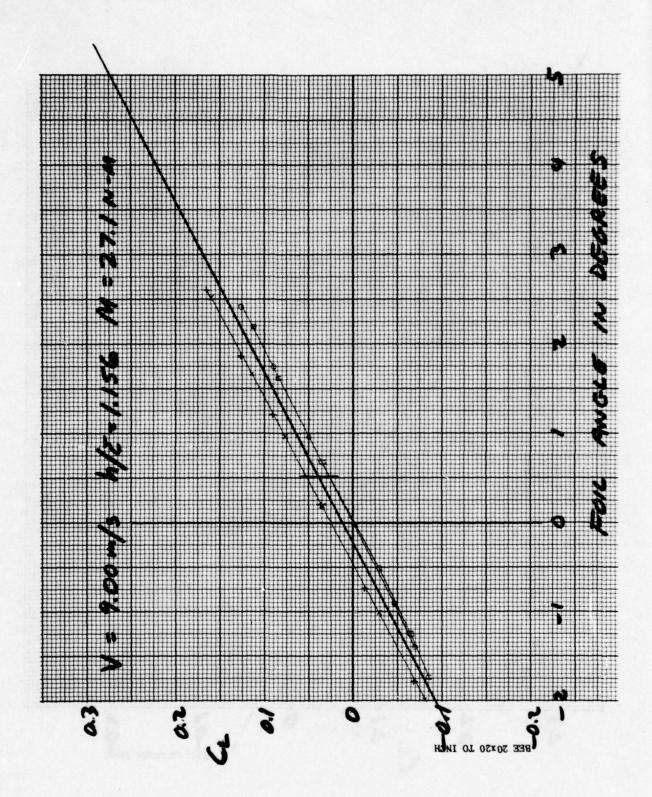


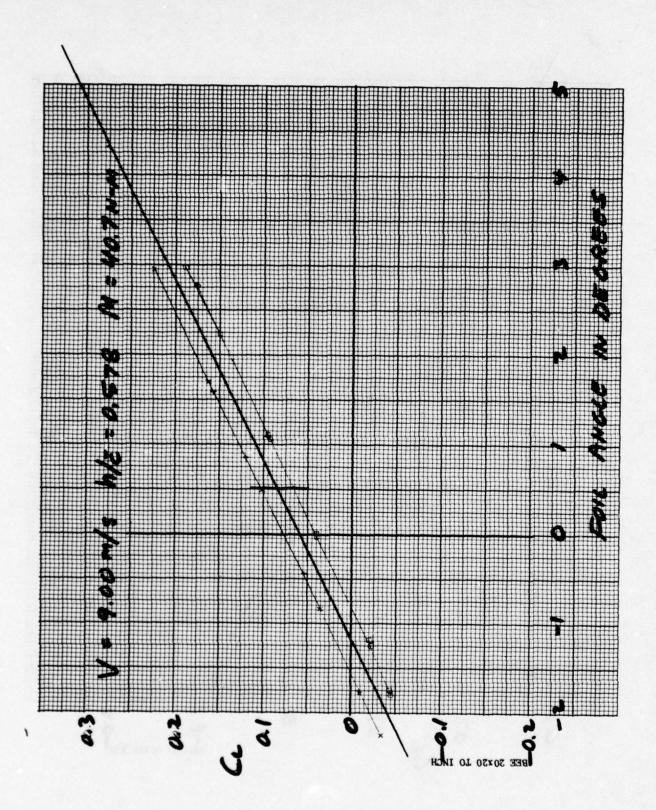


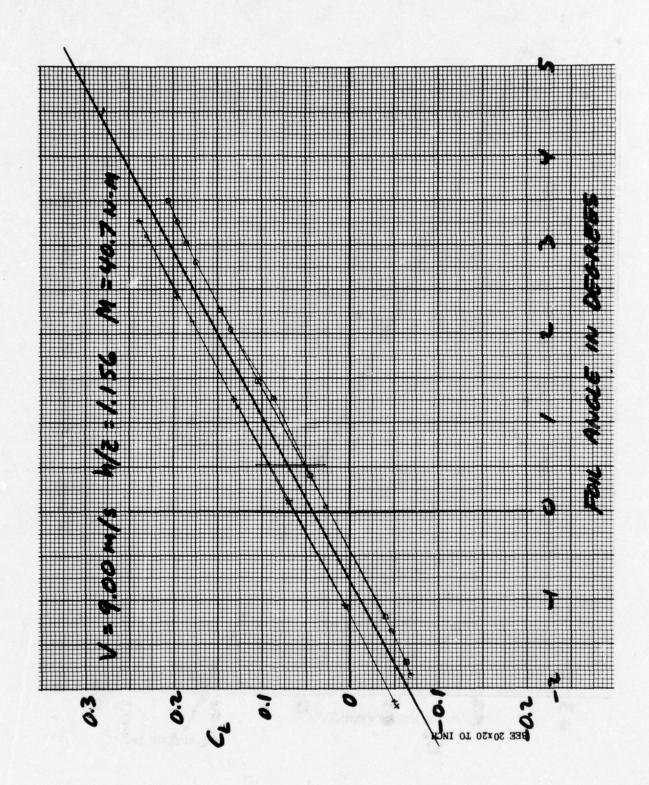


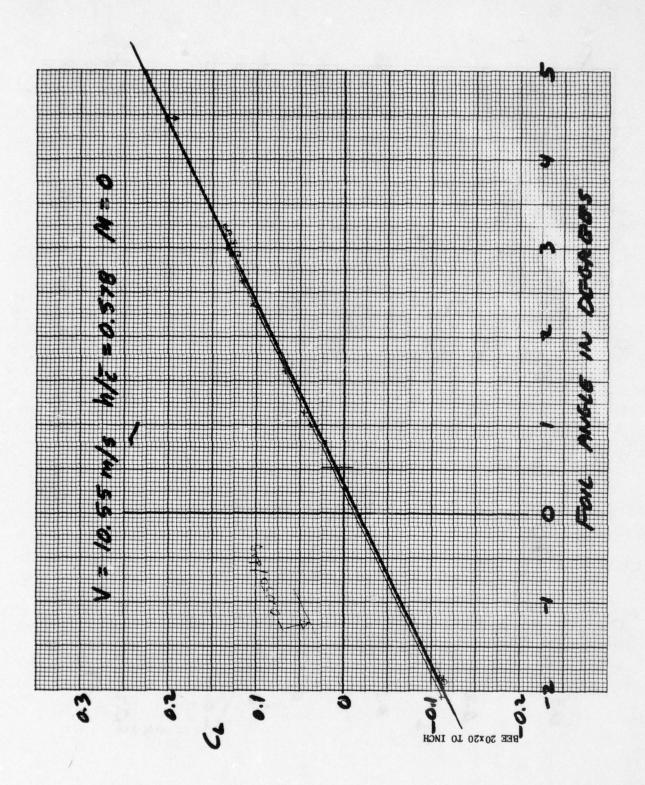


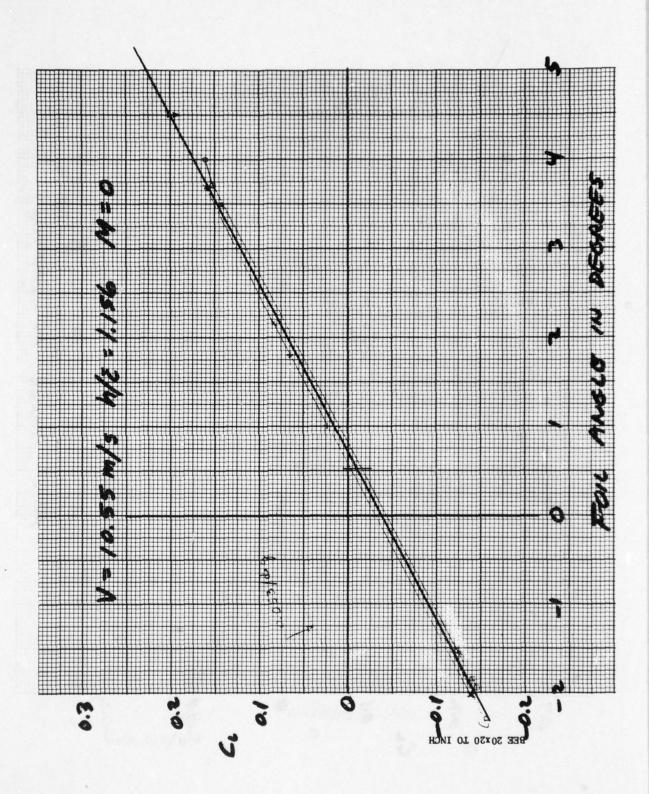


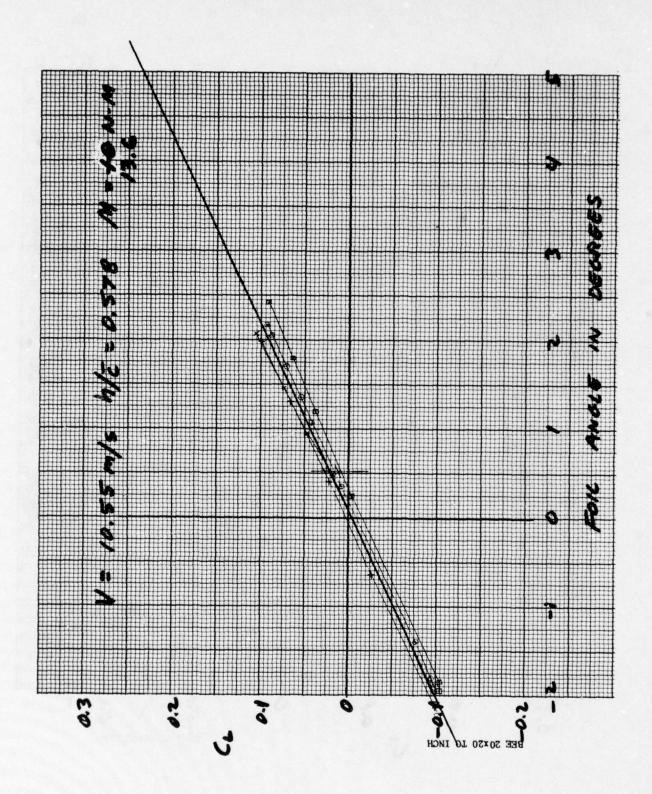


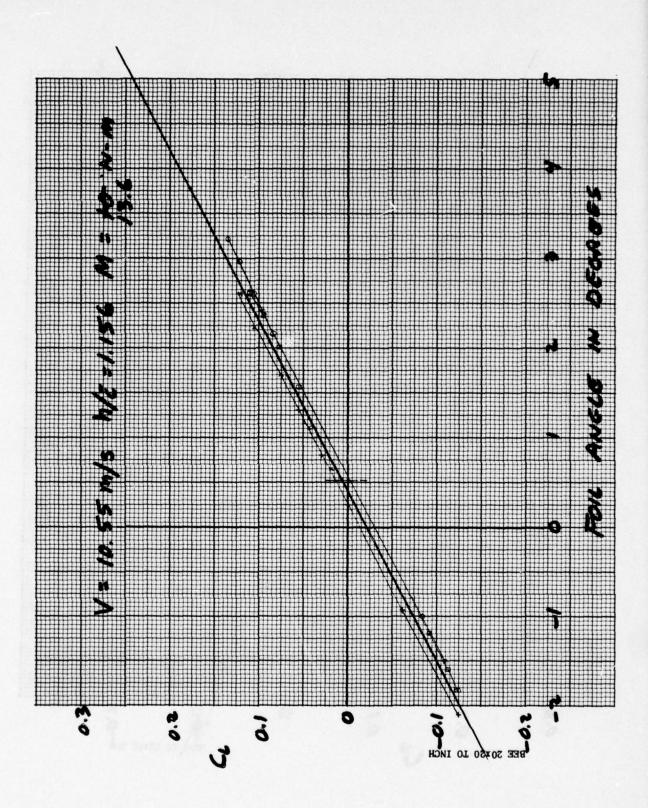


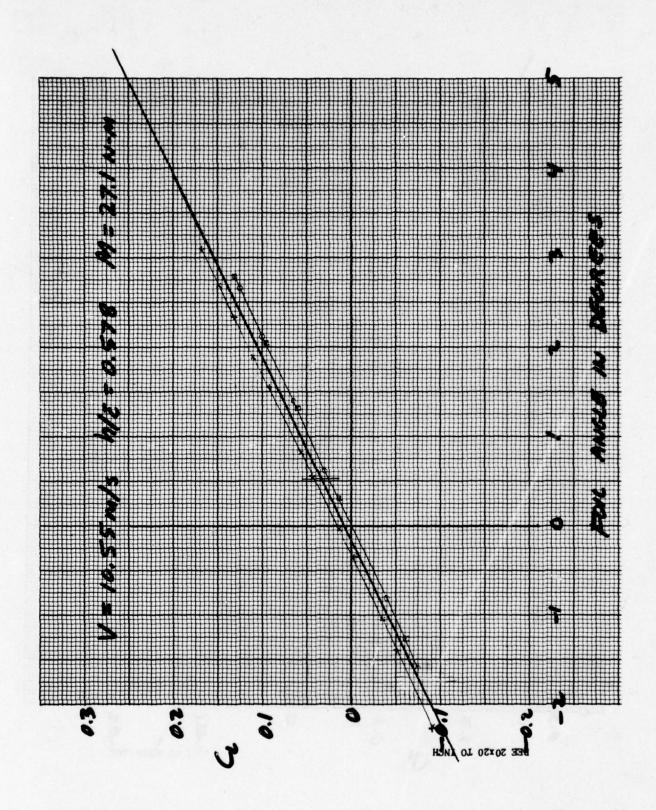


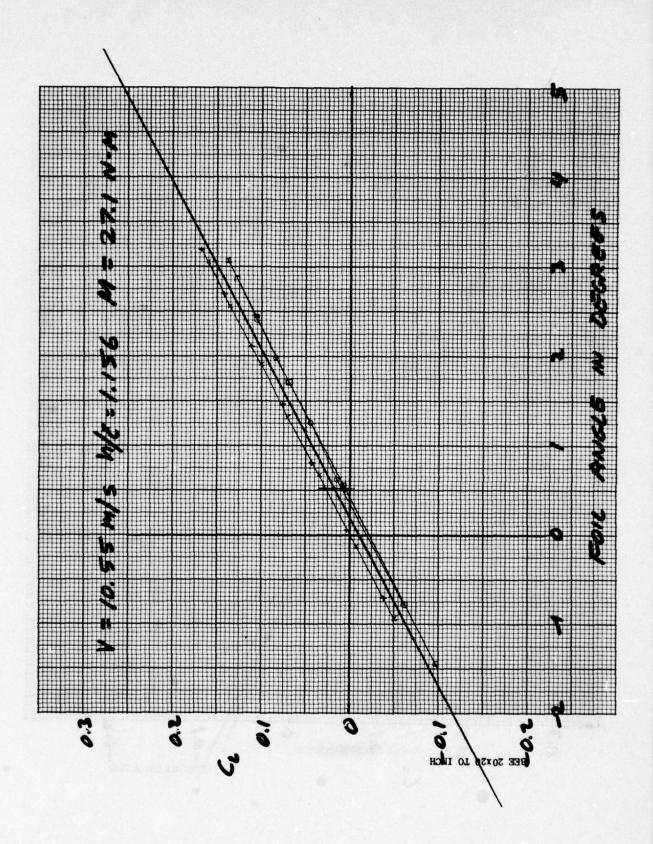


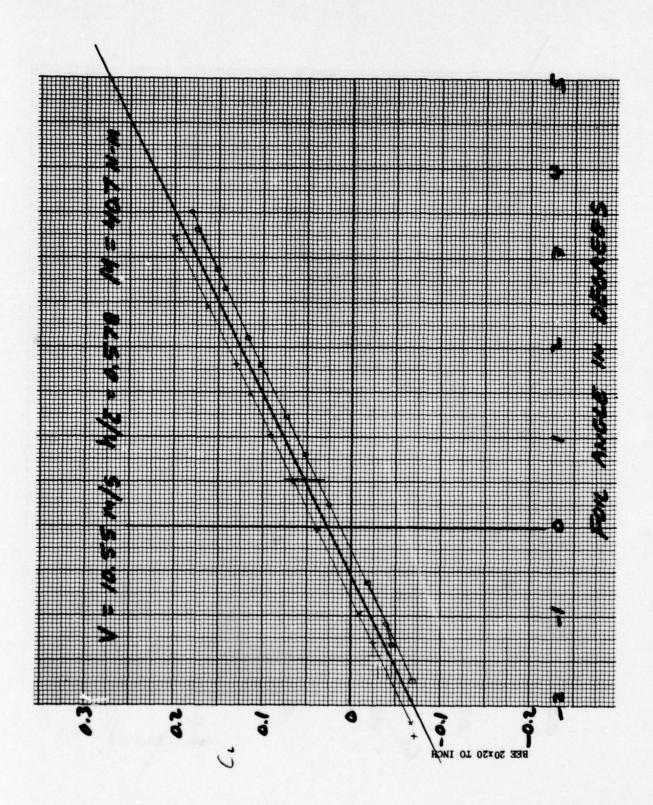


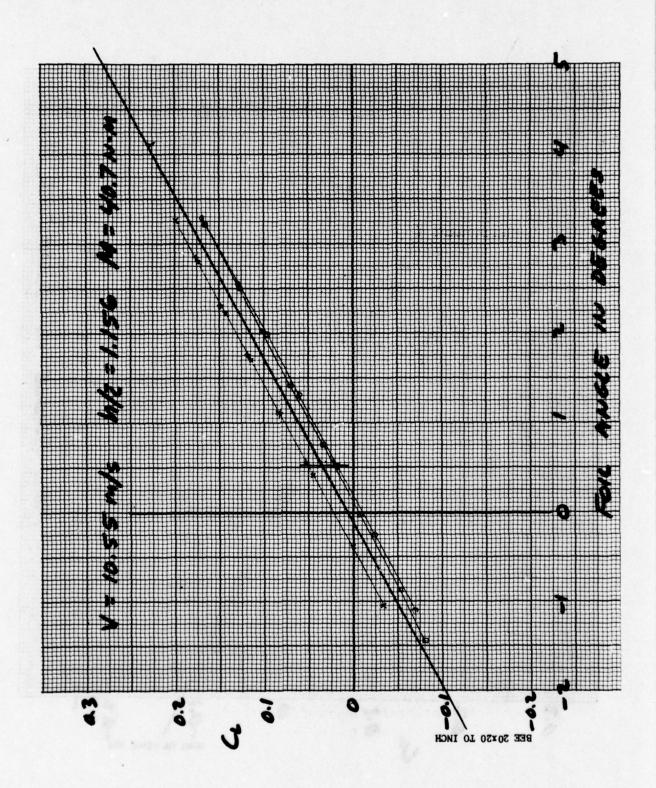


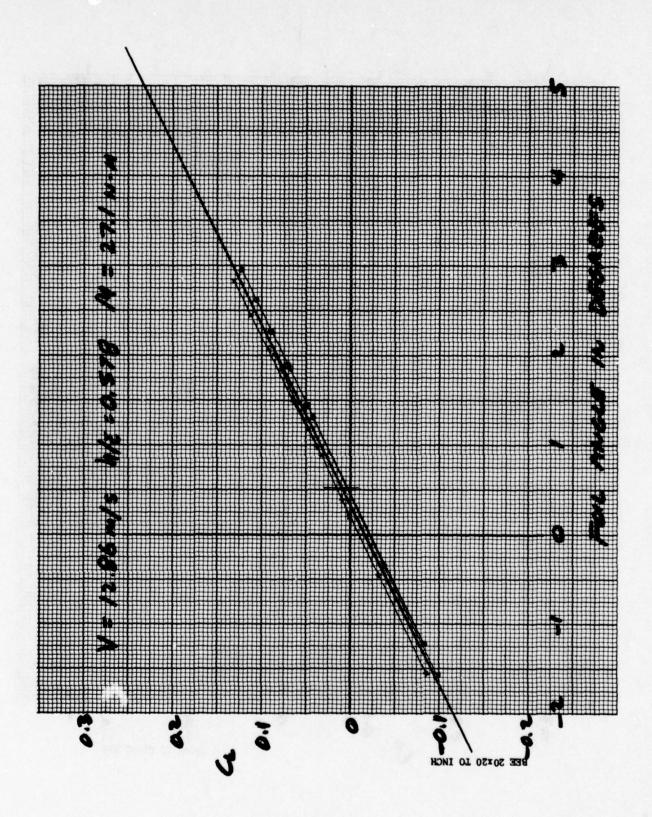


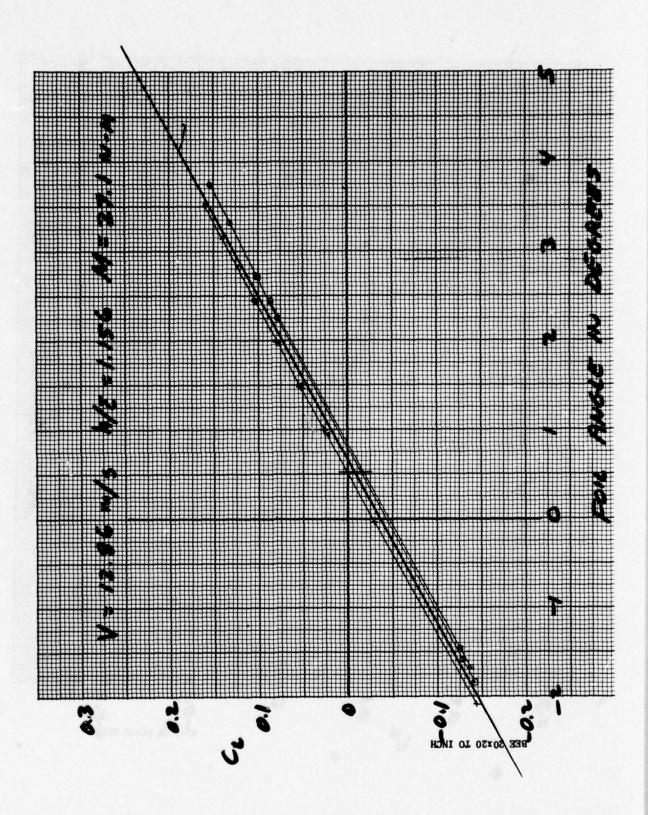


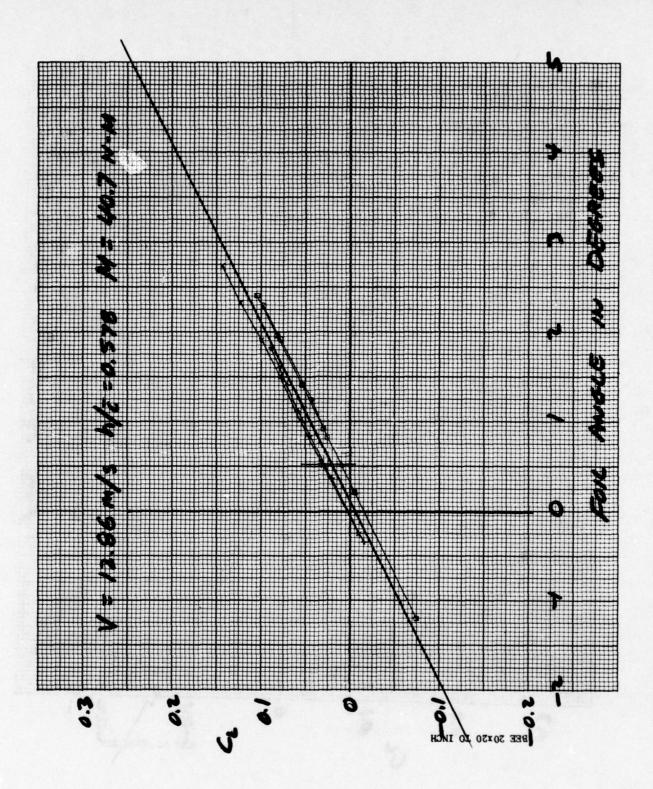


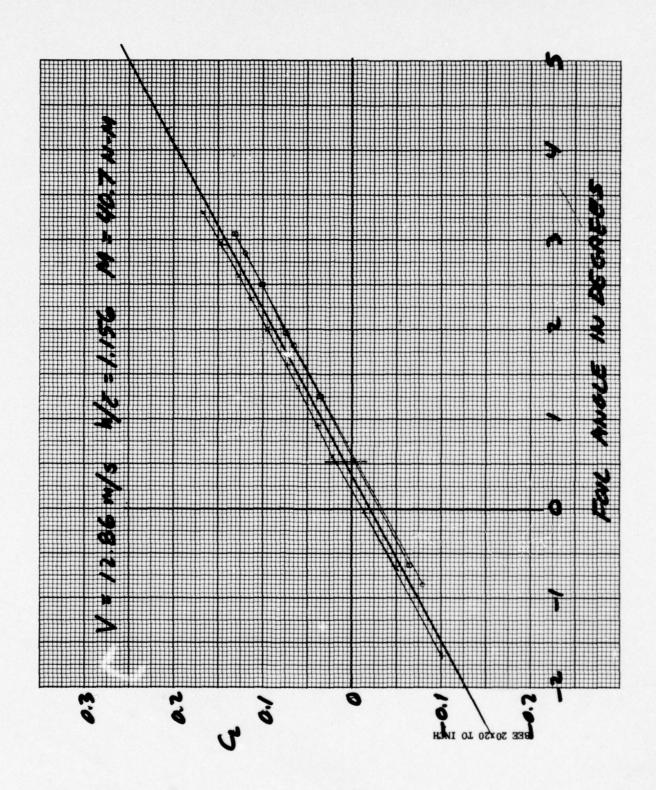












APPENDIX B

ERROR ANALYSIS OF "INDIRECT METHOD"

The "indirect method" of determining the hydrodynamic coefficients, lift- and moment-curve slopes, centers of pressure, and flap effectiveness is shown in Figure B1 (also shown as Figure 1 of main report). This analysis is based on the linear equations developed in the report (Equations [1] through [3]). No attempt is made here to determine the errors introduced by the basic assumptions of those equations, but rather to follow the errors due to measurement of the fundamental experimental parameters through the analysis procedure.

The estimated maximum errors in the fundamental experimental measurements are listed in Table Bl. Based on these errors, the estimated maximum errors in the derived parameter may be determined as follows:

1. LOCATION OF PIVOT POINT (X)

$$X = (X\overline{c})/\overline{c}$$

$$dx/x = d(x\overline{c})/(x\overline{c}) - d\overline{c}/\overline{c}$$

$$dx/x \not \leq d(x\overline{c})/(x\overline{c}) + d\overline{c}/\overline{c}$$

From Table B1.

$$|dx/x| \leq 0.00036 + 0.00012 = 0.00048$$

Thus, maximum percent error in X is about 0.05 percent.

^{*} These estimated maximum errors include both accuracy and precision errors.

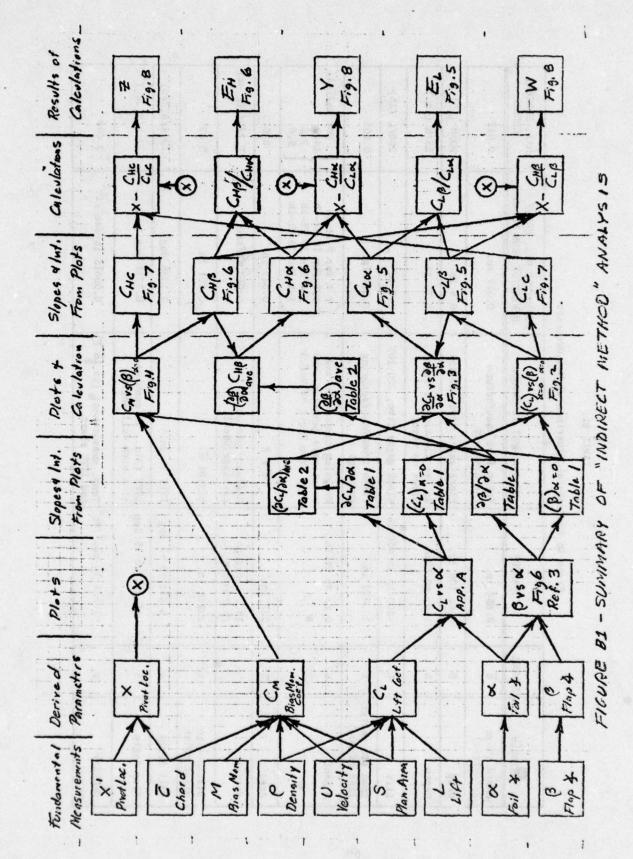


TABLE B1

Error in Fundamental Experimental Measurements

VARIABLE	SYMBOL	VALUES	MEASUREMENT TECHNIQUE	ESTIMATED MAX. ERROR OR DEVIATION FROM VALUE	MAX. PERCENT ERROR
Chord (Mean geometric)	lυ	8.654 in.	Taken from manufactur- ing drawings	0.001 in.	0.012
Drag	Q	0 to 100 lb.	Block gages (two, 50 lb)	0.5 1b	50/D (1b)
Depth	ч	Sin. to 10in.	By eye sighting of lines drawn on strut	0.25 in.	25/h (in.)
Lift	Т	-400 lb to 400 lb	Block gages (two, 200 lb)	2.0 lb	200/L (1b)
Span (To center- line of pod)	В.	13.000 in.	Taken from manufacturing drawings	0.001 in.	0.008
Moment	N	0 to 30 ft-1b	Weighing components and worst case geometry (a=5 deg) from Fig.1 of Ref.3	1.4 for 0 ft-1b 1.4 for 10 ft-1b 1.4 for 20 ft-1b 1.5 for 30 ft-1b	Not defined 14.0 7.0 5.0
Area	s	225 in. ²	G × A	0.047 in. ²	0.020
Velocity	n	14.2 knots to 25.0 knots	Magnetic pickup on carriage wheel	0.017 ft/sec	1.7/U(ft/sec)
Distance to pivot point	οx	2.764 in.	0.3194 c	0.001 in.	0.036
Foil Angle	8	-5 deg to +5 deg	LVDT (1 in.)	0.1336 deg	13.4/a(deg)
Flap Angle	8	-15 deg to 15 deg.	LVDT (3in., in combination with foil angle)	0.7784 deg	77.8/B(deg)
Density	٥	~1.935 lb-sec ² /ft ⁴	~1.935 lb-sec ² /ft ⁴ Temp. measurement (to lo F)	0.00015 lb-sec ² /ft ⁴	0.008

2. BIAS MOMENT COEFFICIENT (CM)

$$C_{M} = M/(1/2 e^{U^{2}S\overline{c}})$$

$$dC_{M}/C_{M} = dM/M - de/e -2dU/U - dS/S - d\overline{c}/\overline{c}$$

$$|dC_{M}/C_{M}| \leq |dM/M| + |de/e| + 2|dU/U| + |dS/S| + |d\overline{c}/\overline{c}|$$

From Table B1,

Not Defined for M = 0 ft-1b
0.14 for M = 10 ft-1b
0.07 for M = 20 ft-1b
0.05 for M = 30 ft-1b
+ 0.00008 + 2
$$\begin{cases}
0.0007 \text{ for } U = 14.2 \text{ Kts} \\
0.0006 \text{ for } U = 17.5 \text{ Kts} \\
0.0005 \text{ for } U = 20.5 \text{ Kts} \\
0.0004 \text{ for } U = 25 \text{ Kts}
\end{cases}$$

+ 0.00020 + 0.00012

All other terms on the right side of the equation are negligible compared to the first term, so

$$\left| dC_{M} \right| \leq \left| dM/M \right| \times \left| C_{M} \right| = \left| dM/(1/2 e^{U^{2} S\overline{c}}) \right|$$

The maximum error in $\mathbf{C}_{\underline{\mathbf{M}}}$ is calculated* as a function of M and U and is shown in Table B2.

^{*} Using $1/2 \rho S\bar{c} = 1.090 \text{ lb-sec}^2/\text{ft}$

TABLE B2 ESTIMATED MAXIMUM ERROR IN BIAS MOMENT COEFFICIENT ($C_{\rm M}$)

U (kts) M (ft-1b)		10	20	30
14.2	0.0022	0.0023	0.0022	0.0025
17.5	0.0015	0.0015	0.0015	0.0006
20.5	0.0011	0.0011	0.0011	0.0012
25.0	0.0007	0.0007	0.0007	0.0008

3. LIFT COEFFICIENT (C,)

$$C_{L} = L/(1/2 \rho U^{2}S)$$

$$dC_{L}/C_{L} = dL/L - d\rho/\rho - 2dU/U - dS/S$$

$$dC_{L}/C_{L} \leq |dL/L| + |d\rho/\rho| + 2 |dU/U| + |dS/S|$$

From Table Bl,

$$dC_{L}/C_{L} \leq 2/L \text{ (1bs)} + 0.00008$$

$$+ 2 \begin{cases} 0.0007 \text{ for } U = 14.2 \text{ Kts} \\ 0.0006 \text{ for } U = 17.5 \text{ Kts} \\ 0.0005 \text{ for } U = 20.5 \text{ Kts} \\ 0.0004 \text{ for } U = 25.0 \text{ Kts} \end{cases}$$

The range for lift is $0 \le L \le 400$ lbs, so the first term on the right is

All other terms are small compared to this one so we may write

$$\begin{vmatrix} dC_L/C_L \end{vmatrix} \leq |dL/L|$$

$$\begin{vmatrix} dC_L \end{vmatrix} \leq |dL/L| \times |C_L| = |dL/(1/2 e^{U^2S})$$

The maximum error in C_L is calculated* for the various velocities as

^{*} Using $1/2 \rho S = 1.512 \text{ lb-sec}^2/\text{ft}^2$

$$|dC_{L}| = 2/(1.512 \text{ U}^{2}(\text{ft/sec})^{2})$$

$$= \begin{cases} 0.0021 \text{ for } U = 14.2 \text{ Kts} \\ 0.0015 \text{ for } U = 17.0 \text{ Kts} \\ 0.0011 \text{ for } U = 20.5 \text{ Kts} \\ 0.0007 \text{ for } U = 25.0 \text{ Kts} \end{cases}$$

4. FOIL ANGLE (%)

The estimated maximum error in foil angle from Table Bl is 0.13 deg.

5. FLAP ANGLE (6)

The estimated maximum error in flap angle from Table Bl is 0.78 deg.

From the derived parameters onward, the analysis technique involves various calculations and plots as shown in Figure B1. The errors in the slopes and intercepts obtained from the plots are determined as followed. For example, take the general case of a plot of one variable (F) versus another variable (G) as shown in Figure B2a. A "best" straight line is drawn by hand. From this line, "best" values for slope and intercept are determined. These are the values listed in the report. Since the variables F and G may have error, the data points may be represented by error boxes as shown in Figure B2b. An infinite number of straight lines may be drawn through all of the boxes. The lines with the maximum and minimum slopes are shown in Figure B2c and the maximum and minimum intercepts are shown in Figure B2d. Thus, the maximum and minimum for the slope and intercept are determined from these four lines. These "bands" of error are carried along through the rest of the analysis by using them in the next calculation or plot.

The types of calculations that are made in the analysis are of the form:

$$F_{ave} = (1/4) \sum_{n=1}^{4} F_n$$
 [B1]

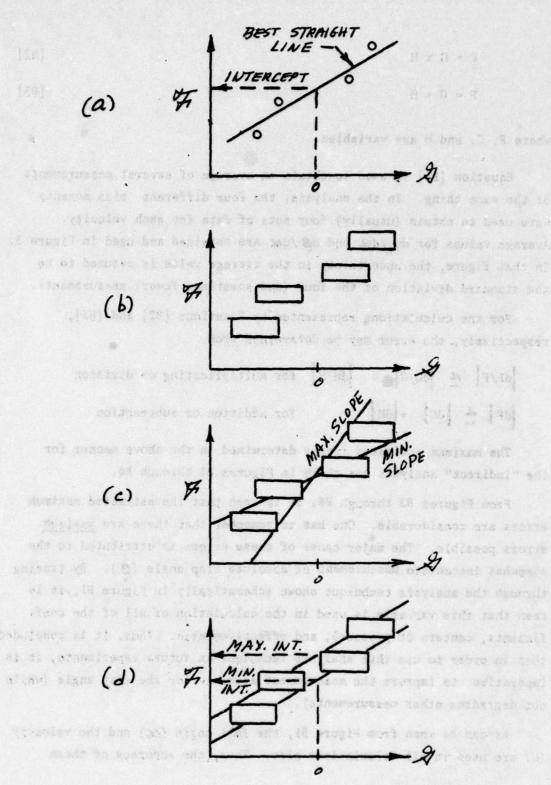


FIGURE B2 - DETERMINATION OF MAXIMUM AND MINIMUM SLOPES AND INTERCEPTS FROM PLOTS

 $F = G \times H$ [B2] F = G + H [B3]

where F, G, and H are variables.

Equation [B1] is used to obtain an average of several measurements of the same thing. In the analysis, the four different bias moments were used to obtain (usually) four sets of data for each velocity. Average values for $dC_L/d\omega$ and $dg/d\omega$ are obtained and used in Figure 3. In that figure, the uncertainty in the average value is assumed to be the standard deviation of the four (and sometimes fewer) measurements.

For the calculations represented by Equations [B2] and [B3], respectively, the error may be determined from

$$|dF/F| \leq |dG/G| + |dH/H|$$
 for multiplicating or division $|dF| \leq |dG| + |dH|$ for addition or subtraction

The maximum estimated errors determined in the above manner for the "indirect" analysis are shown in Figures B3 through B6.

From Figures B3 through B6, it is seen that the estimated maximum errors are considerable. One has to remember that these are maximum errors possible. The major cause of these errors is attributed to the somewhat inaccurate measurement of absolute flap angle (3). By tracing through the analysis technique shown schematically in Figure B1, it is seen that this variable is used in the calculation of all of the coefficients, centers of pressure, and effectivenesses. Thus, it is concluded that in order to use this analysis technique in future experiments, it is imperative to improve the measurement accuracy for the flap angle (while not degrading other measurements).

As can be seen from Figure B1, the foil angle (&) and the velocity (U) are used in all calculations also. Thus, the accuracy of these

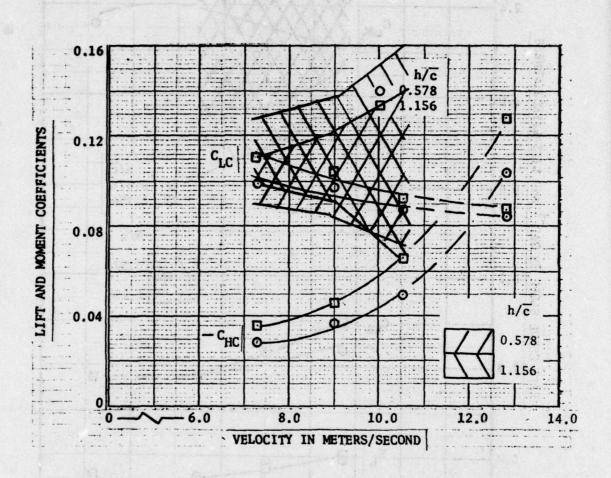


FIGURE B3a - ESTIMATED MAXIMUM ERROR IN $C_{\mbox{\scriptsize LC}}$

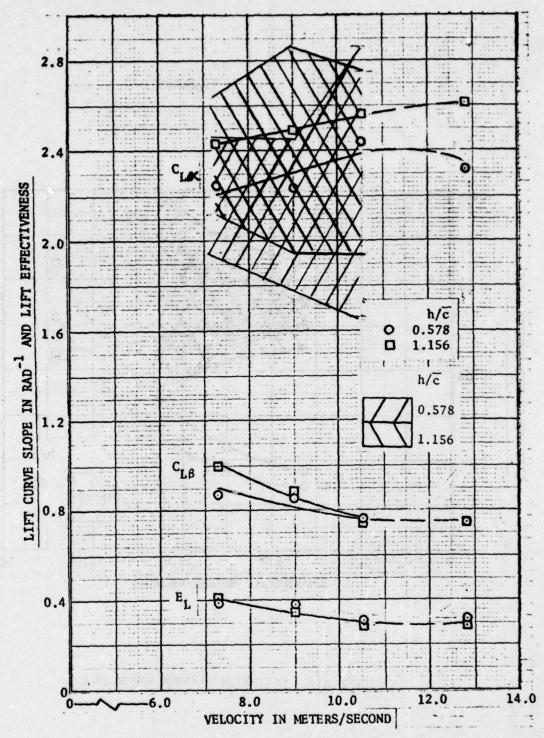


FIGURE B3b - ESTIMATED MAXIMUM ERROR IN CLA

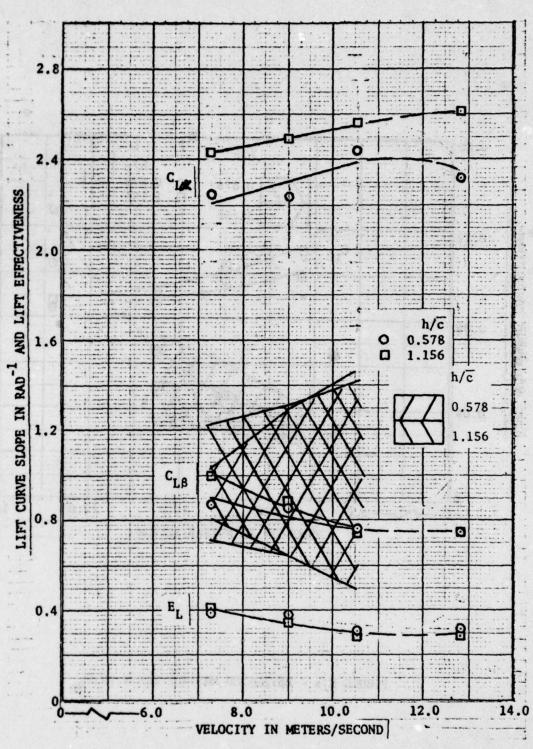


FIGURE B3c - ESTIMATED MAXIMUM ERROR IN CL

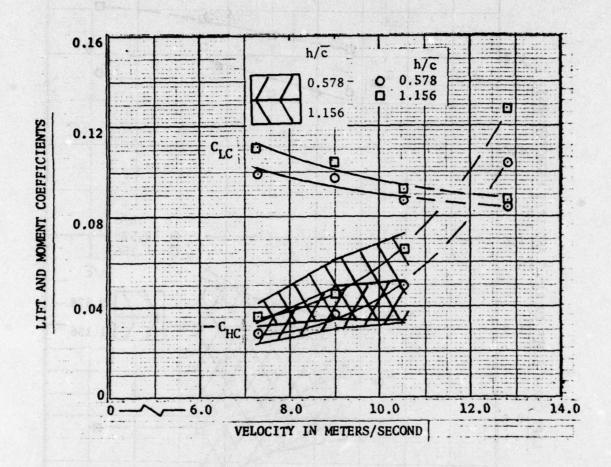


FIGURE 84a - ESTIMATED MAXIMUM ERROR IN CHC

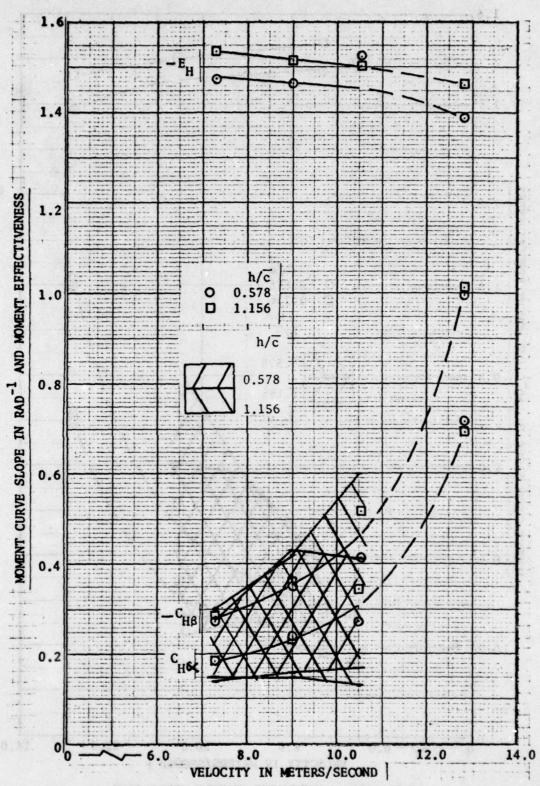


FIGURE B4b - ESTIMATED MAXIMUM ERROR IN CHAR

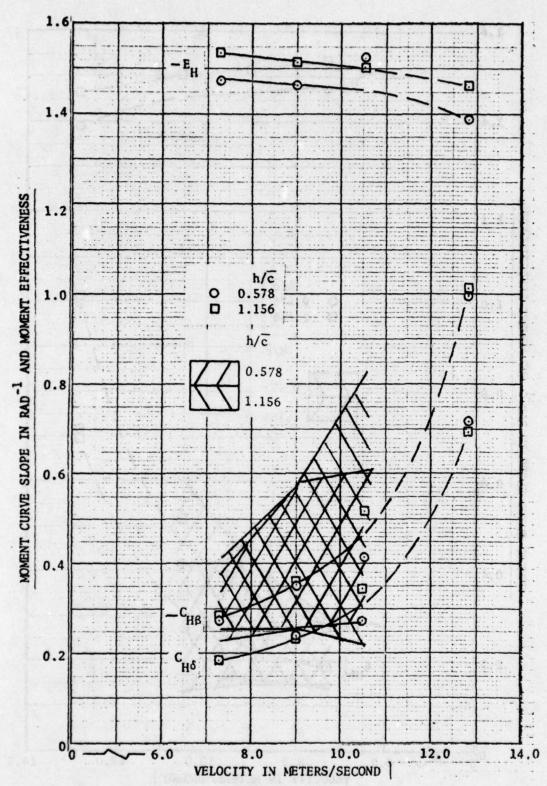


FIGURE B4c - ESTIMATED MAXIMUM ERROR IN CH

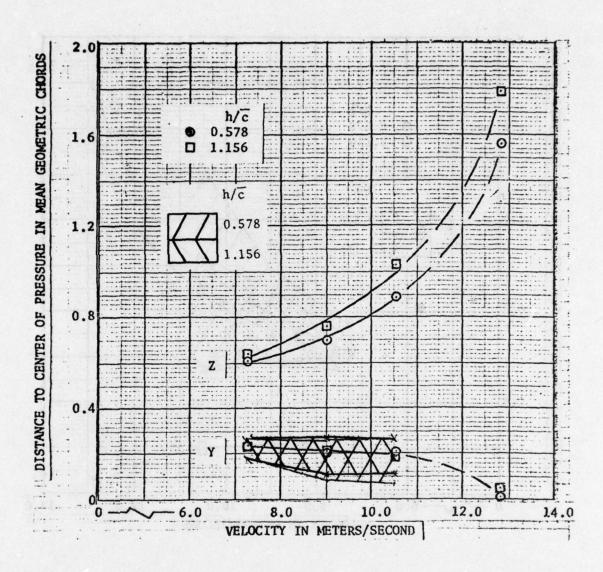


FIGURE B5a - ESTIMATED MAXIMUM ERROR IN Y

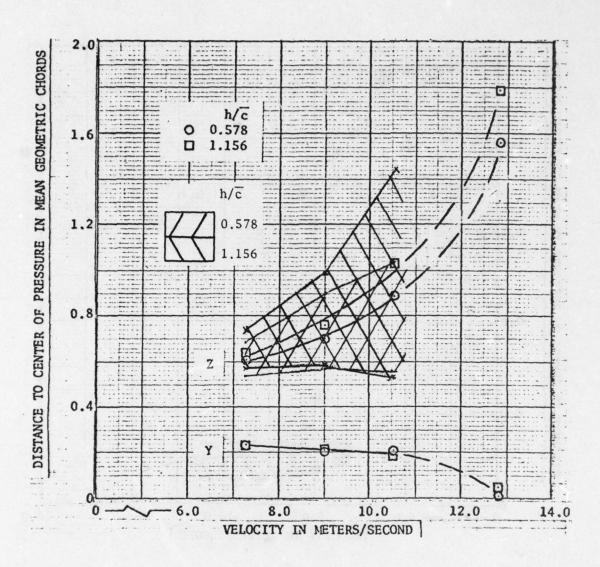


FIGURE B5b - ESTIMATED MAXIMUM ERROR IN Z

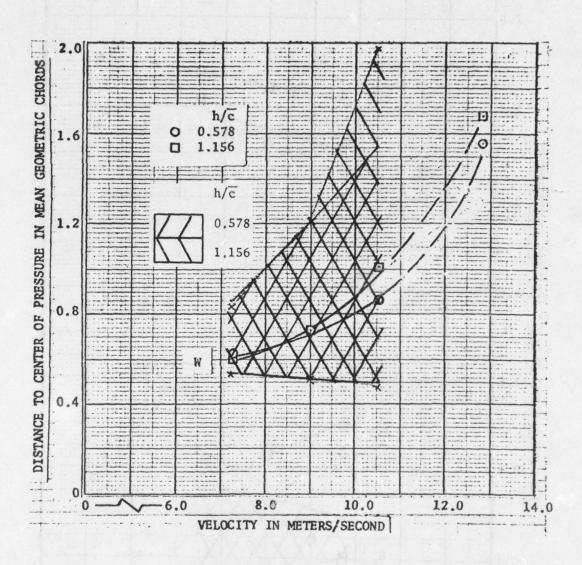


FIGURE B5c - ESTIMATED MAXIMUM ERROR IN W

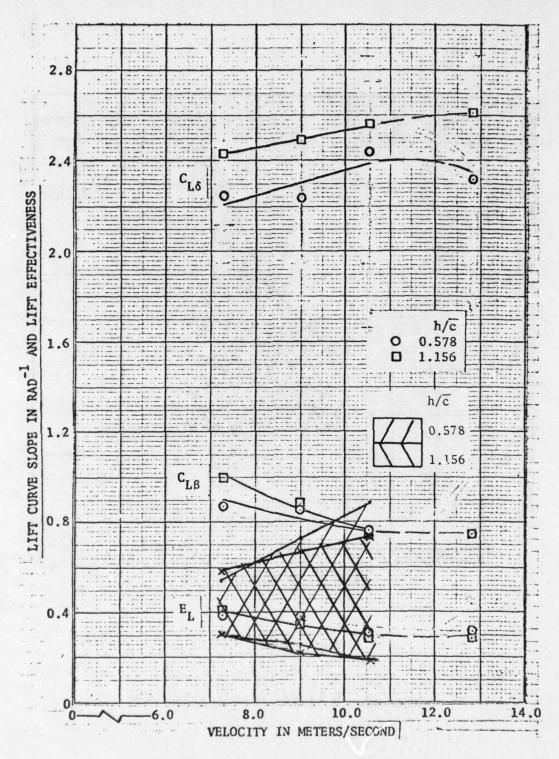


FIGURE B6a - ESTIMATED MAXIMUM ERROR IN $\mathrm{E_{L}}$

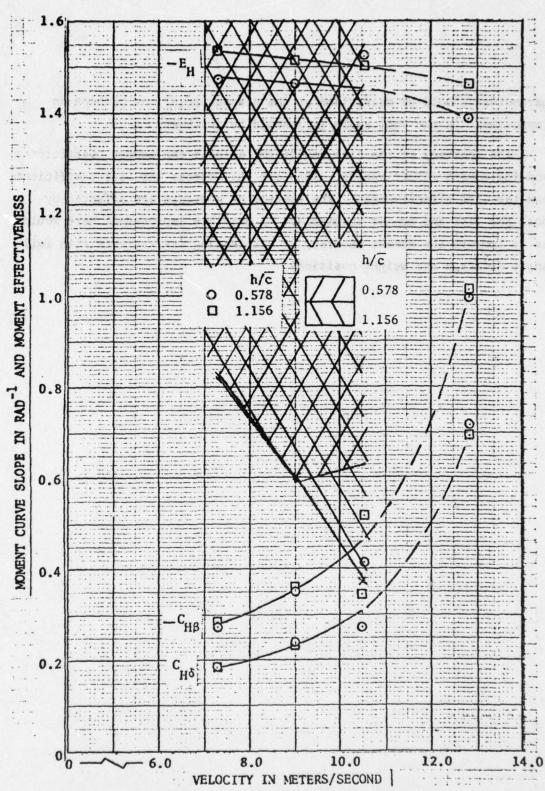


FIGURE B6b - ESTIMATED MAXIMUM ERROR IN $\mathbf{E}_{\mathbf{H}}$

parameters should be maintained at the present level, or perhaps an improvement in the foil angle (x) would be in order.

The accuracy of the bias moment (M) affects the moment coefficients and the moment effectiveness. The lift (L) affects the lift coefficient and the lift effectiveness. The centers of pressure are affected by both the lift and moment accuracies. A possible improvement here would be to improve the moment accuracy by eliminating its variance with foil angle (linkage and weight position).

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- 3. Coder, D.W., R.M. Norton, and B.B. Wisler, Jr., "Hinge Moment Reduction for the AG(EH) Main Strut-Pod-Foil Assembly by Use of Training Edge Tabs," DTNSRDC Report SPD-332-04 (Jun 1976).

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